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Existence and Uniqueness of Solutions for the $p(x)$ -Laplacian Equation with Convection Term

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Abstract: In this paper, we consider the existence and uniqueness of solutions for a quasilinear elliptic equation with a variable exponent and a reaction term depending on the gradient. Based on the surjectivity result for pseudomonotone operators, we prove the existence of at least one weak solution of such a problem. Furthermore, we obtain the uniqueness of the solution for the above problem under some considerations. Our results generalize and improve the existing results.

Keywords: $p(x)$ -Laplacian equation; convection term; pseudomonotone operators; existence results; uniqueness

1. Introduction and Main Results

The $p(x)$ -Laplacian operator has been used in the modelling of electrorheological fluids ([1–3]), in elastic mechanics ([4]), in image restoration ([5–7]) and in magnetostatics problems ([8]). Up to now, a large number of results have been obtained for solutions to equations related to this operator. For instance, we must mention the works of Kefi-Radulescu [9], Saoudi [10], Kefi-Saoudi [11], Xie-Chen [12], Nhan-Chuong-Truong [13], Zhang [14], Zhang-Motreanu [15], Yucedag [16], Yin-Li-Ke [17], Ait Hammou-Azroul-Lahmi [18], Ayazoglu-Ekincioglu [19], Ge-Wang [20], Ge-Lv [21], Ge-Radulescu [22], Heidarkhani-Afrouzi-Moradi-Caristi-Ge [23], Ge-Zhou-Wu [24], Fan [25] and the references therein. In relation to the regularity for solutions of differential equations with $p(x)$ -Laplacian operator, we refer the readers to [26–36], respectively, and the references therein.

In this paper, we consider the following problem

$$\begin{cases} -\operatorname{div}(|\nabla u|^{p(x)-2}\nabla u) = f(x, u, \nabla u), & \text{in } \Omega, \\ u = 0, & \text{on } \partial\Omega, \end{cases} \quad (1)$$

where Ω is a smooth bounded domain in \mathbb{R}^N , $N \geq 2$, $f : \Omega \times \mathbb{R} \times \mathbb{R}^N \mapsto \mathbb{R}$ is a Carathéodory function, $p(\cdot)$ is a logarithmic Hölder continuous with values in $(1, N)$ and satisfies the following condition:

(H_p) there is a vector $\xi_0 \in \mathbb{R}^N \setminus \{0\}$ such that for any $x \in \Omega$, the map $t \mapsto p(x + t\xi_0)$ is monotone on $t \in \{t|x + t\xi_0 \in \Omega\}$.

If $p(x) \equiv p$ is a constant, the equation in the problem (1) is of the form

$$\begin{cases} -\operatorname{div}(|\nabla u|^{p-2}\nabla u) = f(x, u, \nabla u), & \text{in } \Omega, \\ u = 0, & \text{on } \partial\Omega. \end{cases} \quad (2)$$

Problems of form (2) arise naturally as stationary states of certain models in fluid mechanics. Therefore, it is important to obtain information about the existence and nonexistence of solutions for this problem.

There is a rich body of literature concerning problem (2), see, e.g., [37–41] and the references therein. Using topological methods, Montenegro [37] and Ruiz [38] obtained the existence of positive solutions for problem (2), respectively. Later, Zou [39] proved that (2) has a positive solution by using the fixed point theorem with the a priori estimates. Very recently, the authors in [41] used sub-supersolution techniques with Schaefer’s fixed point theorem to prove the existence of a positive and a negative solution for problem (2).

The key research point in the paper is that the right-hand side of problem (1) depends on the solution u and its gradient ∇u . The expression $f(x, u, \nabla u)$ is often referred to as a convection term. Since the nonlinearity f depends on the gradient ∇u , problem (1) does not have a variational structure, so the variational methods cannot be applied directly. In order to overcome this difficulty, Yin, Li and Ke in [17], by using Krasnoselskii’s fixed point theorem on the cone, proved the existence of positive solutions for problem (1) under certain assumptions. Very recently, the authors in [18] used the topological degree theory for a class of demicontinuous operators of generalized (S_+) type to prove the existence of at least one weak solution for problem (1) under the following assumption on $f(x, t, \xi)$:

(H_f) There exists $k \in L^{\frac{p(x)}{p(x)-1}}(\Omega)$, $q \in C(\Omega)$ with $1 < q^- \leq q(x) \leq q^+ < p^-$ and $C > 0$ such that

$$|f(x, t, \xi)| \leq C(k(x) + |t|^{q(x)-1} + |\xi|^{q(x)-1})$$

for a.a. $x \in \Omega$ and all $(t, \xi) \in \mathbb{R} \times \mathbb{R}^N$.

It is well known that the condition (H_f) means that the nonlinearity f has sub- p linear growth. However, this condition is quite restrictive and eliminates several nonlinearities. Motivated by the aforementioned works, in the present paper, we consider the problem (1) in the case when the nonlinearity f satisfies the subcritical growth condition. To this end, we assume that $f : \Omega \times \mathbb{R} \times \mathbb{R}^N \mapsto \mathbb{R}$ is a Carathéodory function that satisfies the following assumptions:

(f_1) There exists $k \in L^{\frac{r(x)}{r(x)-1}}(\Omega)$, $1 < r(x) < p^*(x) := \frac{Np(x)}{N-p(x)}$ and $C > 0$ such that

$$|f(x, t, \xi)| \leq C(k(x) + |t|^{r(x)-1} + |\xi|^{p(x)\frac{r(x)-1}{r(x)}})$$

for a.a. $x \in \Omega$ and all $(t, \xi) \in \mathbb{R} \times \mathbb{R}^N$.

(f_2) There exists $w \in L^1(\Omega)$ and $b_1, b_2 \geq 0$ with $b_1 + b_2\lambda_*^{-1} < 1$ such that

$$f(x, t, \xi)t \leq b_1|\xi|^{p(x)} + b_2|t|^{p(x)} + w(x)$$

for a.a. $x \in \Omega$ and all $(t, \xi) \in \mathbb{R} \times \mathbb{R}^N$, where λ_* is the infimum of all eigenvalues of the nonhomogeneous eigenvalue problem

$$\begin{cases} -\operatorname{div}(|\nabla u|^{p(x)-2}\nabla u) = \lambda|u|^{p(x)-2}u, & \text{in } \Omega, \\ u = 0, & \text{on } \partial\Omega, \end{cases}$$

Remark 1. It is well known that (see ([42] Theorem 3.4)), if condition (H_p) holds, then we have $\lambda_* :=$

$$\inf_{u \in W_0^{1,p(x)}(\Omega) \setminus \{0\}} \frac{\int_{\Omega} |\nabla u|^{p(x)} dx}{\int_{\Omega} |u|^{p(x)} dx} > 0.$$

Remark 2. The following function satisfies conditions (f_1) – (f_2) , where, for simplicity, we drop the x -dependence,

$$f(t, \xi) = -c_1|t|^{r(x)-2}t + c_2|\xi|^{p(x)-1}, \quad \forall t \in \mathbb{R}, \quad \forall \xi \in \mathbb{R}^N,$$

with $p(x) < r(x) < p^*(x)$, $c_1 \geq 0$ and $0 \leq c_2 < \frac{1}{1+\lambda_{1,\alpha}}$.

We are now in the position to state our main result.

Theorem 1. Assume that (H_p) and (f_1) – (f_2) hold. Then, problem (1) has at least one solution.

Next, we consider the uniqueness of solutions of (1). To this end, we also need the following hypotheses on the convection term:

(f_3) There exists $b_3 \geq 0$ such that

$$(f(x, t, \xi) - f(x, s, \xi))(t - s) \leq b_3 |t - s|^{p(x)}$$

for a.a. $x \in \Omega$ and all $(t, \xi) \in \mathbb{R} \times \mathbb{R}^N$.

(f_4) There exists $b_4 \geq 0$ such that

$$|f(x, t, \xi) - f(x, t, \eta)| \leq b_4 |\xi - \eta|^{p(x)-1}$$

for a.a. $x \in \Omega$ and all $(t, \xi) \in \mathbb{R} \times \mathbb{R}^N$.

Our uniqueness result reads as follows.

Theorem 2. Assume that (H_p) and (f_1) – (f_4) hold. If, in addition, $2 \leq p(x)$ for all $x \in \overline{\Omega}$, then problem (1) has a unique weak solution provided

$$2^{p^+} \left(\left[b_3 + \frac{b_4}{q^-} \right] \lambda_{**}^{-1} + b_4 \frac{q^+ - 1}{q^-} \right) < 1.$$

To the best of our knowledge, our setting is more general than those of [17,18] and our method contrasts with other treatments of (1). The functional framework contains the generalized Lebesgue and Sobolev spaces with variable exponents and our technique is based on the surjectivity result for pseudomonotone operators.

This paper is designed as follows: First, we briefly review the definitions and collect some preliminary results for the variable exponent Sobolev spaces $W_0^{1,p(x)}(\Omega)$ and we recall the surjectivity result for pseudomonotone operators. Finally, we complete the proofs of Theorems 1 and 2 of this paper.

2. Preliminaries

In order to discuss problem (1), we start with the definition of the variable exponent Lebesgue spaces $L^{p(x)}(\Omega)$ and the the variable exponent Sobolev spaces $W_0^{1,p(x)}(\Omega)$, and some properties of them; for more details, see [43–46].

Let Ω and p be as in Section 1. Let us denote

$$C_+(\overline{\Omega}) = \{h \in C(\overline{\Omega}) : h(x) > 1 \text{ for every } x \in \overline{\Omega}\}.$$

For any $h \in C_+(\overline{\Omega})$, we write

$$h^- := \min_{x \in \overline{\Omega}} h(x) \text{ and } h^+ := \max_{x \in \overline{\Omega}} h(x).$$

For any $p \in C_+(\overline{\Omega})$, we define the variable exponent Lebesgue space by

$$L^{p(x)}(\Omega) = \left\{ u \text{ is a measurable real valued function with } \int_{\Omega} |u|^{p(x)} dx < +\infty \right\}.$$

We consider this space to be endowed with the so-called Luxemburg norm:

$$|u|_{p(x)} = \inf \left\{ \lambda > 0 : \int_{\Omega} \left| \frac{u(x)}{\lambda} \right|^{p(x)} dx \leq 1 \right\}.$$

We define the variable exponent Sobolev spaces $W^{1,p(x)}(\Omega)$ by

$$W^{1,p(x)}(\Omega) = \{u \in L^{p(x)}(\Omega) : |\nabla u| \in L^{p(x)}(\Omega)\},$$

equipped with the norm

$$\|u\| = |u|_{p(x)} + |\nabla u|_{p(x)}. \tag{3}$$

The space $W_0^{1,p(x)}(\Omega)$ is defined by the closure of $C_0^\infty(\Omega)$ in $W^{1,p(x)}(\Omega)$. With these norms, the spaces $L^{p(x)}(\Omega)$, $W_0^{1,p(x)}(\Omega)$ and $W^{1,p(x)}(\Omega)$ are separable reflexive Banach spaces; see [44,46] for details.

Proposition 1. ([44]) Set $\rho(u) = \int_\Omega |u|^{p(x)} dx$. Let $u \in L^{p(x)}(\Omega)$, then, we have

- (i) $|u|_{p(x)} < 1 (= 1; > 1) \Leftrightarrow \rho(u) < 1 (= 1; > 1)$.
- (ii) If $|u|_{p(x)} \geq 1$, then $|u|_{p(x)}^{p^-} \leq \rho(u) \leq |u|_{p(x)}^{p^+}$.
- (iii) If $|u|_{p(x)} \leq 1$, then $|u|_{p(x)}^{p^+} \leq \rho(u) \leq |u|_{p(x)}^{p^-}$.

Proposition 2. ([44,46])

(1) If $q \in C_+(\bar{\Omega})$ and $q(x) < p^*(x)$ for every $x \in \Omega$, then the embedding from $W_0^{1,p(x)}(\Omega)$ to $L^{q(x)}(\Omega)$ is continuous and compact.

(2) The Poincaré's inequality in $W_0^{1,p(x)}(\Omega)$ holds, that is, there is a constant $C_0 > 0$ such that

$$|u|_{p(x)} \leq C_0 |\nabla u|_{p(x)}, \quad \forall u \in W_0^{1,p(x)}(\Omega).$$

It follows from (1) of Proposition 2 that there exists $c_\theta > 0$ such that

$$|u|_{q(x)} \leq c_\theta \|u\|, \quad \forall u \in W_0^{1,p(x)}(\Omega).$$

We note that by (2) of Proposition 2, it follows that $|\nabla u|_{p(x)}$ is an equivalent norm in $W_0^{1,p(x)}(\Omega)$. We will use the equivalent norm in the following discussion and write $\|u\| = |\nabla u|_{p(x)}$ for simplicity.

Let us recall some definitions we will use later.

Definition 1. Let X be a reflexive Banach space, X^* its dual space and let $\langle \cdot, \cdot \rangle$ denote its duality pairing. Let $\mathcal{L} : X \rightarrow X^*$; then, \mathcal{L} is called

- (i) to satisfy the (S_+) -property if $u_n \rightharpoonup u$ in X and $\limsup_{n \rightarrow +\infty} \langle \mathcal{L}(u_n), u_n - u \rangle \leq 0$ imply $u_n \rightarrow u$ in X ;
- (ii) pseudomonotone if $u_n \rightharpoonup u$ in X and $\limsup_{n \rightarrow +\infty} \langle \mathcal{L}(u_n), u_n - u \rangle \leq 0$ imply $\mathcal{L}(u_n) \rightharpoonup \mathcal{L}(u)$ and $\langle \mathcal{L}(u_n), u_n \rangle \rightarrow \langle \mathcal{L}(u), u \rangle$.

The main tool is based on the surjectivity result for pseudomonotone operators from Carl-Le-Motreanu ([47] Theorem 2.99), which is now stated for the reader's convenience.

Lemma 1. Let X be a real reflexive Banach space, and assume that $\mathcal{L} : X \rightarrow X^*$ is a bounded, coercive and pseudomonotone operator. Then, there exists a solution to the equation $\mathcal{L}(u) = v$, where $v \in X^*$.

Now, we denote the $p(x)$ -Laplacian operator $\mathcal{L} : W_0^{1,p(x)}(\Omega) \rightarrow (W_0^{1,p(x)}(\Omega))^*$ defined by

$$\langle \mathcal{L}(u), v \rangle = \int_\Omega |\nabla u|^{p(x)-2} \nabla u \cdot \nabla v dx$$

for all $u, v \in W_0^{1,p(x)}(\Omega)$, where $(W_0^{1,p(x)}(\Omega))^*$ denotes the dual space of $W_0^{1,p(x)}(\Omega)$ and $\langle \cdot, \cdot \rangle$ denotes the pairing between $W_0^{1,p(x)}(\Omega)$ and $(W_0^{1,p(x)}(\Omega))^*$. The properties of double phase operator \mathcal{L} are summarized in the following proposition; see Fan–Zhang ([43] Theorem 3.1).

Proposition 3. *Let \mathcal{L} be as before and set $E = W_0^{1,p(x)}(\Omega)$. Then, $\mathcal{L} : E \rightarrow E^*$ is a continuous, bounded, strictly monotone operator of type (S_+) , i.e., if $u_n \rightharpoonup u$ in E and $\limsup_{n \rightarrow +\infty} \langle \mathcal{L}(u_n) - \mathcal{L}(u), u_n - u \rangle \leq 0$, implies $u_n \rightarrow u$ in E .*

3. Proof of Theorem 1

In this section, the proof of the existence of nontrivial weak solutions for (1) is provided by applying the Lemma 1 under suitable assumptions. Recall that u is said to be a weak solution of (1) if

$$\int_{\Omega} |\nabla u|^{p(x)-2} \nabla u \cdot \nabla v \, dx = \int_{\Omega} f(x, u, \nabla u) v \, dx \tag{4}$$

is satisfied for all test functions $v \in E$. Taking Proposition 2(1) into account, along with the growth conditions in (f_1) , we see that the definition of a weak solution is well defined.

We now turn to the proof of Theorem 1.

Proof of Theorem 1. Define the Nemytskii operator $\bar{N}_f : E \subseteq L^{r(x)}(\Omega) \rightarrow L^{\frac{r(x)}{r(x)-1}}(\Omega)$ defined by

$$(\bar{N}_f u)(x) = f(x, u(x), \nabla u(x)).$$

Moreover, let $I^* : L^{\frac{r(x)}{r(x)-1}}(\Omega) \rightarrow E^*$ be the adjoint operator for the embedding of $I : E \rightarrow L^{r(x)}(\Omega)$. We then define

$$N_f = I^* \circ \bar{N}_f : E \rightarrow E^*,$$

which is well-defined by assumption (f_1) . We set

$$\mathbb{L}(u) = \mathcal{L}(u) - N_f(u).$$

In view of Lemma 1, it suffices to show the following: (A_1) \mathbb{L} is bounded; (A_2) \mathbb{L} is pseudomonotone; (A_3) \mathbb{L} is coercive.

Verification of (A_1) : By virtue of the growth condition f_1 , we easily know that \mathbb{L} maps bounded sets into bounded sets. Thus, (A_1) is satisfied.

Verification of (A_2) : Let $\{u_n\}_{n=1}^{\infty} \subset E$ be a sequence such that

$$u_n \rightharpoonup u \text{ in } E \text{ and } \limsup_{n \rightarrow +\infty} \langle \mathbb{L}(u_n), u_n - u \rangle \leq 0. \tag{5}$$

Due to the compact embeddings $E \hookrightarrow L^{r(x)}(\Omega)$, we can deduce that

$$u_n \rightarrow u \text{ in } L^{r(x)}(\Omega). \tag{6}$$

Hence, from (f_1) , the Hölder inequality and the boundedness of $\{u_n\}_{n=1}^{\infty}$, it follows that

$$\begin{aligned}
 & \left| \int_{\Omega} f(x, u_n, \nabla u_n)(u_n - u) dx \right| \\
 & \leq C \int_{\Omega} k(x) |u_n - u| dx + C \int_{\Omega} |u_n|^{r(x)-1} |u_n - u| dx \\
 & \quad + C \int_{\Omega} |\nabla u_n|^{p(x) \frac{r(x)-1}{r(x)}} |u_n - u| dx \\
 & \leq 2C |k|_{\frac{r(x)}{r(x)-1}} \|u_n - u\|_{r(x)} + 2C \| |u_n|^{r(x)-1} \|_{\frac{r(x)}{r(x)-1}} \|u_n - u\|_{r(x)} \\
 & \quad + 2C \| |\nabla u_n|^{p(x) \frac{r(x)-1}{r(x)}} \|_{\frac{r(x)}{r(x)-1}} \|u_n - u\|_{r(x)} \\
 & \leq 2C |k|_{\frac{r(x)}{r(x)-1}} \|u_n - u\|_{r(x)} + 2C (\|u_n\|_{r(x)}^{r^+-1} + \|u_n\|_{r(x)}^{r^--1}) \|u_n - u\|_{r(x)} \\
 & \quad + 2C \left(\|\nabla u_n\|_{p(x)}^{p^+(1-\frac{1}{r^+})} + \|\nabla u_n\|_{p(x)}^{p^-(1-\frac{1}{r^-})} \right) \|u_n - u\|_{r(x)}.
 \end{aligned} \tag{7}$$

This fact combined with (6) implies that

$$\lim_{n \rightarrow +\infty} \int_{\Omega} f(x, u_n, \nabla u_n)(u_n - u) dx = 0. \tag{8}$$

At this point, we can pass to the limit in (4) replacing u with u_n and v with $u_n - u$. Thus, we obtain that

$$\limsup_{n \rightarrow +\infty} \langle \mathcal{L}(u_n), u_n - u \rangle = \limsup_{n \rightarrow +\infty} \langle \mathbb{L}(u_n), u_n - u \rangle \leq 0. \tag{9}$$

Therefore, it follows that $u_n \rightarrow u$ because \mathcal{L} is a mapping of type (S_+) . Moreover, due to the continuity of \mathbb{L} , we have that $\mathbb{L}(u_n) \rightarrow \mathbb{L}(u)$ in E^* which proves that \mathbb{L} is pseudomonotone. Therefore, (A_2) is satisfied.

Verification of (A_3) : To this end, we need only to show that

$$\lim_{\|u\| \rightarrow +\infty} \frac{\langle \mathbb{L}(u), u \rangle}{\|u\|} = +\infty. \tag{10}$$

Indeed, for any $u \in E$ with $\|u\| > 1$, it follows from (f_2) that

$$\begin{aligned}
 \langle \mathbb{L}(u), u \rangle &= \int_{\Omega} |\nabla u|^{p(x)} dx - \int_{\Omega} f(x, u, \nabla u) u dx \\
 &\geq \int_{\Omega} |\nabla u|^{p(x)} dx - b_1 \int_{\Omega} |\nabla u|^{p(x)} dx - b_2 \int_{\Omega} |u|^{p(x)} dx \\
 &\quad - \int_{\Omega} |w(x)| dx \\
 &\geq \int_{\Omega} |\nabla u|^{p(x)} dx - b_1 \int_{\Omega} |\nabla u|^{p(x)} dx - b_2 \lambda_*^{-1} \int_{\Omega} |\nabla u|^{p(x)} dx \\
 &\quad - |w|_1 \\
 &= (1 - b_1 - b_2 \lambda_*^{-1}) \int_{\Omega} |\nabla u|^{p(x)} dx - |w|_1.
 \end{aligned} \tag{11}$$

Therefore, since $p^- > 1$ and $b_1 + b_2 \lambda_*^{-1} < 1$, by using (11) and Proposition 1, we have

$$\langle \mathbb{L}(u), u \rangle \geq (1 - b_1 - b_2 \lambda_*^{-1}) \|u\|^{p^-} - |w|_1, \tag{12}$$

which implies that (10) is satisfied and, hence, \mathbb{L} is coercive. Thus, (A_3) is satisfied.

Therefore, all the assumptions of Lemma 1 are satisfied; hence, there exists a $u_0 \in E$ such that $\mathbb{L}(u) = 0$, which concludes the proof of Theorem 1. \square

Finally, we give the proof of Theorem 2.

Proof of Theorem 2. Let $u_1, u_2 \in E$ be two weak solutions of (1). Considering the weak formulation of u_1 and u_2 , by choosing $v = u_1 - u_2$ as a test function, we have

$$\int_{\Omega} |\nabla u_1|^{p(x)-2} \nabla u_1 \cdot \nabla (u_1 - u_2) dx = \int_{\Omega} f(x, u_1, \nabla u_1) (u_1 - u_2) dx$$

and

$$\int_{\Omega} |\nabla u_2|^{p(x)-2} \nabla u_2 \cdot \nabla (u_1 - u_2) dx = \int_{\Omega} f(x, u_2, \nabla u_2) (u_1 - u_2) dx.$$

Subtracting the above two equations, we have

$$\begin{aligned} & \int_{\Omega} (|\nabla u_1|^{p(x)-2} \nabla u_1 - |\nabla u_2|^{p(x)-2} \nabla u_2) \cdot \nabla (u_1 - u_2) dx \\ &= \int_{\Omega} (f(x, u_1, \nabla u_1) - f(x, u_2, \nabla u_2)) (u_1 - u_2) dx. \end{aligned} \tag{13}$$

Moreover, since $p(x) \geq 2$ for all $x \in \bar{\Omega}$, then we have the following inequality (see [48]):

$$\begin{aligned} & (|\nabla u_1(x)|^{p(x)-2} \nabla u_1(x) - |\nabla u_2(x)|^{p(x)-2} \nabla u_2(x)) \cdot \nabla (u_1(x) - u_2(x)) \\ & \geq \left(\frac{1}{2}\right)^{p(x)} |\nabla (u_1(x) - u_2(x))|^{p(x)}. \end{aligned} \tag{14}$$

Using assumptions (f_3) - (f_4) and (14) in (13), then it follows from the Young inequality that

$$\begin{aligned} & \left(\frac{1}{2}\right)^{p^+} \int_{\Omega} |\nabla (u_1(x) - u_2(x))|^{p(x)} dx \\ & \leq \int_{\Omega} (|\nabla u_1|^{p(x)-2} \nabla u_1 - |\nabla u_2|^{p(x)-2} \nabla u_2) \cdot \nabla (u_1 - u_2) dx \\ & = \int_{\Omega} (f(x, u_1, \nabla u_1) - f(x, u_2, \nabla u_2)) (u_1 - u_2) dx \\ & = \int_{\Omega} (f(x, u_1, \nabla u_1) - f(x, u_2, \nabla u_1)) (u_1 - u_2) dx \\ & \quad + \int_{\Omega} (f(x, u_2, \nabla u_1) - f(x, u_2, \nabla u_2)) (u_1 - u_2) dx \\ & \leq b_3 \int_{\Omega} |u_1 - u_2|^{p(x)} dx + b_4 \int_{\Omega} |\nabla (u_1 - u_2)|^{p(x)-1} |u_1 - u_2| dx \\ & \leq b_3 \int_{\Omega} |u_1 - u_2|^{p(x)} dx + b_4 \int_{\Omega} \frac{|\nabla (u_1 - u_2)|^{p(x)}}{\frac{p(x)}{p(x)-1}} dx \\ & \quad + b_4 \int_{\Omega} \frac{|u_1 - u_2|^{p(x)}}{p(x)} dx \\ & \leq b_3 \lambda_*^{-1} \int_{\Omega} |\nabla (u_1 - u_2)|^{p(x)} dx + b_4 \frac{p^+ - 1}{p^-} \int_{\Omega} |\nabla (u_1 - u_2)|^{p(x)} dx \\ & \quad + \frac{b_4}{p^-} \lambda_*^{-1} \int_{\Omega} |\nabla (u_1 - u_2)|^{p(x)} dx \\ & = \left(\left[b_3 + \frac{b_4}{p^-} \right] \lambda_*^{-1} + b_4 \frac{p^+ - 1}{p^-} \right) \int_{\Omega} |\nabla (u_1 - u_2)|^{p(x)} dx. \end{aligned} \tag{15}$$

Consequently, when $2^{p^+} \left(\left[b_3 + \frac{b_4}{p^-} \right] \lambda_*^{-1} + b_4 \frac{p^+ - 1}{p^-} \right) < 1$, it follows from inequality (15) that $u_1 = u_2$ and so the solution of (1) is unique. The proof is complete. \square

4. Conclusions

In this paper, we have discussed the $p(x)$ -Laplacian equation with a convection term on the gradient. Due to the presence of the gradient ∇u in the term $f(x, u, \nabla u)$, problem (1) does not have a generally variational structure, so the variational methods are not applicable. In view of this difficulty, few papers pay attention to the existence of solutions to problem (1) in its general form. In order to overcome this difficulty, in this paper, we use the theory of pseudomonotone operators to obtain the existence of solutions for problem (1), formulated in the paper as Theorem 1. Furthermore, under some additional conditions of the data, the uniqueness of weak solutions is shown, formulated in the paper as Theorem 2. One example is given to show the effectiveness of our results.

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