

Article

A High-Voltage and Low-Noise Power Amplifier for Driving Piezoelectric Stack Actuators

Lisong Xu ^{1,2,*}, Hongwen Li ², Pengzhi Li ³ and Chuan Ge ^{1,2}

¹ University of Chinese Academy of Sciences, Beijing 100049, China; gechmail@163.com

² Changchun Institute of Optics, Fine Mechanics and Physics, Chinese Academy of Science, Changchun 130033, China; lihongwen@ciomp.ac.cn

³ School of Computing and Engineering, University of Gloucestershire, The Park, Cheltenham GL502RH, UK; pli2@glos.ac.uk

* Correspondence: xuls0520@mails.jlu.edu.cn; Tel.: +86-431-8670-8163; Fax: +86-431-8670-8180

Received: 20 September 2020; Accepted: 4 November 2020; Published: 15 November 2020



Abstract: In this paper, based on the principles of general operational amplifiers, a high-voltage operational amplifier is developed. Considering the influences of piezoelectric stack actuators on the circuit, a novel structure using the high-voltage operational amplifier as a noninverting amplifier is proposed. Because of the simple circuit principles and the voltage feedback control structure, the proposed power amplifier has the advantages of low noise and small size, and it can be realized by discrete electric elements easily. In the application of precision positioning, a power amplifier using the proposed circuit principles for driving piezoelectric stack actuators is designed, simulated, and tested. The simulated results show that the proposed power amplifier could conform to the theory of the circuit. The experimental results show that the designed power amplifier conforms to the simulation, the bandwidth of the power amplifier is about 57 kHz, and the ripple of the power amplifier is less than 2 mV. Furthermore, the output of the proposed power amplifier maintains the same type of wave within in a large range of frequency, while the input is the sinusoidal or square wave, and the resolution of the mechanism which the power amplifier is applied in is about 4.5 nm. By selecting the critical electronic elements and using feedback control, the proposed circuit structure is able to realize a low-cost and high-performance power amplifier to drive piezoelectric stack actuators flexibly, which is the novel work of the paper.

Keywords: piezoelectric stack actuator; high-voltage operational amplifier; power amplifier; low output voltage ripple; precision positioning

1. Introduction

Piezoelectric stack actuators have been widely used in robotics, scanning probe microscopies, industrial precision positioning systems, and biomedical engineering because of their small size, high displacement resolution, and lack of electromagnetic interference [1–8]. In these applications, power amplifiers are important subsystems, and low-noise and high-voltage power amplifiers are needed to achieve the performance of piezoelectric stack actuators. There are usually two types of power amplifiers: voltage amplifiers and charge amplifiers [9–14]. Because voltage amplifiers have the advantages of simple structure and high bandwidth, they have been widely adopted for commercial power amplifiers [13,15]. Many such voltage amplifiers have been proposed by References [16–23], and the power amplifier can also be used to estimate the force and displacement of the piezoelectric stack actuator [24]. Reference [25] studies and implements a 15 W driver for piezoelectric stack actuators; the power losses of the driver can be reduced because of the proposed circuit structure, and the output voltage ripples are about 40 mV. Reference [13] proposes a power amplifier based on the error-amplified

principle, and the output voltage ripples are about 20 mV. In Reference [26], a dual amplifier able to deliver a 300 kHz sine wave of 20 V_{pp} amplitude with 100 nF load is proposed. Aiming at low cost, Reference [15] designs the power amplifiers by audio power amplifiers, because of their high output current and high frequency bandwidth, and the power amplifiers can drive capacitive loads with the output signal frequencies reaching 20 kHz. Reference [27] implements an innovative amplifier, using isolation amplifier and subtracting amplifier; the amplifier presents a voltage gain of approximately 100 and an output swing of 200 V. These works in the mentioned referenced papers are innovative; however, some problems still exist: high output noise ripples, high price, low output voltage, or complex circuit structure. Reference [13] shows that the core components of power amplifiers are high-voltage operational amplifiers with high current and low output noise. At present, there are commercial products from Apex Microtechnology (Tucson, Arizona, USA) [28], but they have disadvantages of high price and little choice; it could not satisfy some applications in which the amplifiers should be low in cost.

The structure and the principles of power amplifiers of low cost, small size, simple structure, and high precision are proposed in this paper. The proposed power amplifier is mainly based on the structure of the general operational amplifiers, and it takes the circuit model of piezoelectric stack actuators into account. The power amplifier could be realized by discrete electronic elements flexibly. Then a prototype power amplifier is produced. The performance of the developed prototype power amplifier is simulated by Cadence/PSPICE (San Jose, CA, USA) software and tested by a series of experiments. The novelty of the paper is that the proposed circuit structure is simple, and the function of each part is clear, which makes the realization and the test of the circuit easier. Furthermore, the circuit is realized by discrete electronic components, which makes it easy to adjust the circuit parameters to drive various piezoelectric stack actuators.

The organization of this paper is as follows. Section 1 gives a brief introduction. In Section 2, the structure and the principle of the power amplifier are analyzed explicitly; they reveal the feasibility of the design profoundly and show the design is applicable. Section 3 selects the crucial electronic components. Section 4 shows the simulation results of the power amplifier. Section 5 presents the experimental results of the developed power amplifier. Finally, Section 6 draws the main conclusions.

2. The Circuit Principles of the Power Amplifier

2.1. The Schematic of the Proposed High-Voltage Operational Amplifier

Based on the principles of general operational amplifiers, the schematic of the high-voltage operational amplifier is shown as Figure 1. According to Figure 1, the high-voltage operational amplifier is composed by three stages.

The input stage

The input stage of the high-voltage operational amplifier is a differential amplifier circuit. The circuit is composed by Q_{2-5} , D_{1-3} and some resistances, and the pair transistor Q_4 is the critical element of the circuit. The pair transistor and Q_{2-3} realize a CC-CE combined amplifier; R_1 and D_3 realize a voltage clamp circuit, which makes the voltage between base of Q_2 and emitter of Q_4 constant. The current source of the differential amplifier circuit realized by Q_5 and R_9 ensures the symmetry of the circuit and provides an appropriate operating point for stage 2. The relationships between the input and output can be expressed as follows:

$$V_1(t) = V_Q + A_1(V_{i+}(t) - V_{i-}(t)), \quad (1)$$

where A_1 is the magnification of the circuit, V_Q is the output bias, and $V_1(t)$ is the voltage signal described in the Figure 1. V_Q can be expressed as Equation (2), and the needed operation point V_{Q2} for

stage 2 can be expressed by Equation (3). In Equations (2) and (3), V_{BE} is the drop voltage of the diode and V_{CC} is the voltage of the positive power supply.

$$V_Q = V_{CC} - (0.5I_b R_3 + V_{BE}), \quad (2)$$

$$V_{Q2} = V_{CC} - (I_a R_2 + V_{BE}). \quad (3)$$

Making $I_a = I_b$ and $R_3 = 2R_2$, and then $V_Q = V_{Q2}$, the designed parameters can satisfy the requirement of the operational point of the stage 2 perfectly, which is the important role of the stage 1. The CC-CE combined amplifier has excellent frequency characteristics, and the magnification A_1 is a constant value during DC to thousands Hz.

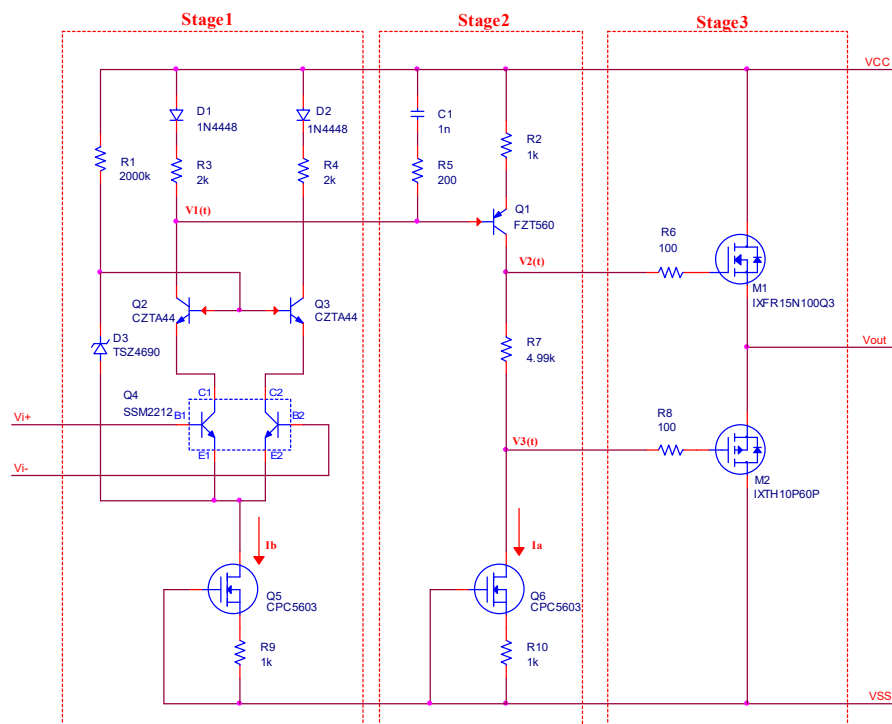


Figure 1. The schematic of the high-voltage operational amplifier.

The amplify stage

Stage 2 of the circuit is configured as a common-emitter BJT with a current source load. The circuit always needs a stable operating point, which demands that the input signal is very small and has no effect on the operating point. The input voltage $V_1(t)$ described in Figure 1 can be expressed as follows:

$$V_1(t) = V_{Q2} + V_S(t), \quad (4)$$

where V_{Q2} is the operation point and $V_S(t)$ is the input signal. Based on the circuit theory, it is proved that the circuit only amplifies the input signal, and the relationship between the input and output signal can be expressed by Equation (5), where A_2 is the magnification of the circuit and $V_2(t)$ is the voltage signal described in Figure 1.

$$V_2(t) = A_2 V_S(t). \quad (5)$$

An ideal current source has infinite internal resistance, but the characteristic of the current source realized by depletion MOSFETs is shown as Figure 2. During the operating range, the actual current source has a dynamic internal resistance, which is expressed in Figure 2.

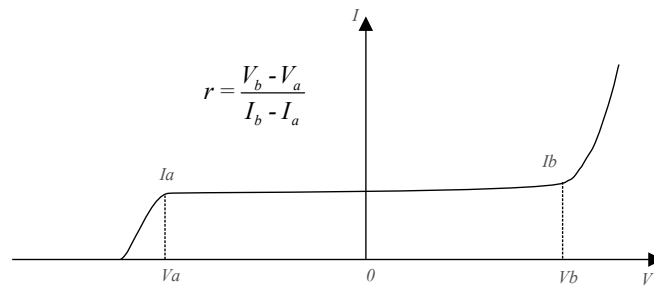


Figure 2. The dynamic resistance of the current source.

Taking the model of the BJT into account, the model of the circuit within the bandwidth is shown as Figure 3. Ignoring R_5 and C_1 , the magnification of the circuit is expressed as follows:

$$A_2(s) = -\frac{r i_c(s)}{i_b(s) R_{be} + (i_b(s) + i_c(s)) R_2} = -\frac{r \beta}{R_{be} + (1 + \beta) R_2} \tag{6}$$

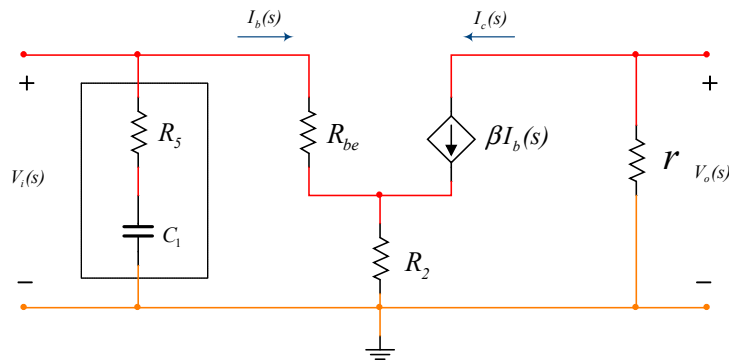


Figure 3. The equivalent circuit of the voltage-amplifying stage.

The dynamic internal resistance of the current source implemented by depletion MOSFETs is numerically big, so that the magnification of the circuit is also very big. The high-frequency attenuation is implemented by the network of R_5 and C_1 , which improves the frequency characteristics of the circuit and enhances the stability of the circuit.

The output stage

The MOSFETs M_1 and M_2 are the critical elements of the output stage, which is a general class B amplifier circuit. In the circuit, R_7 is used to eliminate crossover distortion; R_6 and R_8 are used to reduce the effect of the input capacitance of M_1 and M_2 . The circuit has advantages of a large output current and high bandwidth, and its magnification can be expressed as $A_3(s) \approx 1$.

When the power supply for the amplifier has the function of current protection or the output current of the amplifier is moderate, the circuit in Figure 1 can be applied directly. The practical circuit is shown in Figure 4 for when the demanded currents exceed the maximum currents of M_1 and M_2 . As the parallel circuits of the class B amplifier are identical, the output current of the circuit can be expressed as Equation (7), which has enlarged the output current N times.

$$\begin{cases} I_{P1} = I_{P2} = \dots = I_{PN} \\ I_{N1} = I_{N2} = \dots = I_{NN} \end{cases} \tag{7}$$

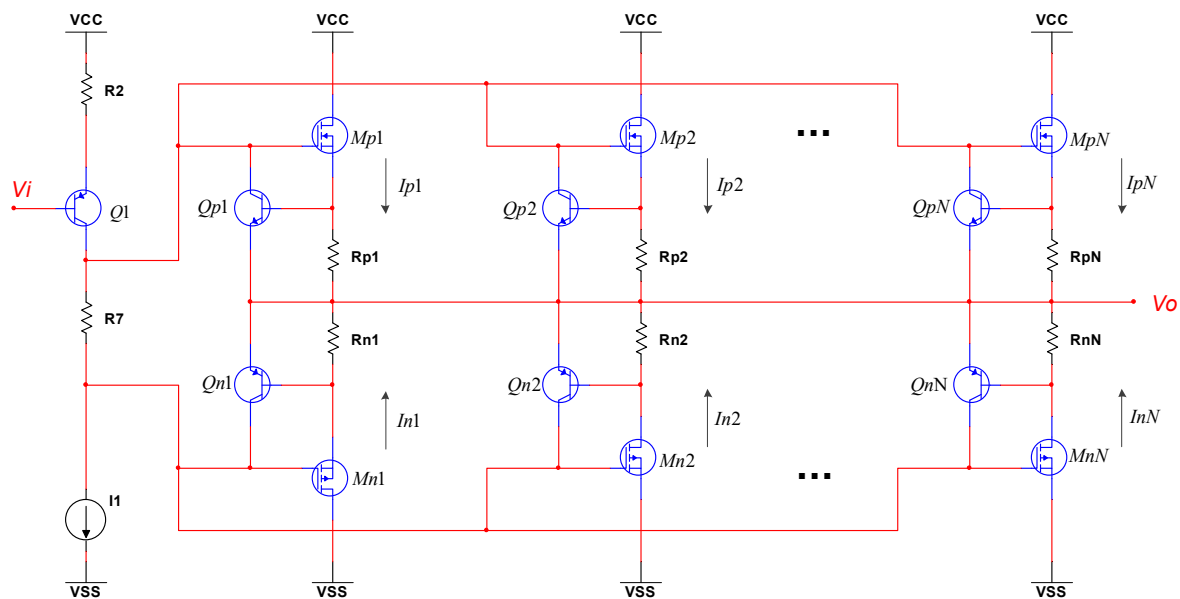


Figure 4. The power-amplifier circuit with multi-level parallel connection.

Considering that the parameters of discrete electronic elements are inconsistent, the currents of Mni and Mpi need to be limited, so the MOSFETs are not damaged by transient current. In the circuit, the current of Mpi is limited by Qpi and Rpi , and the current of Mni is limited by Qni and Rni . The parallel connection of the class B amplifier is a major design method in the design of power amplifiers for piezoelectric stack actuators, which is different from a general operational amplifier, as the output current of a general operational amplifier is always about several mA.

In the actual model of MOSFETs, there are input capacitances, which are shown in Figure 5. As the number of the parallel connections of the class B amplifier increases, the bandwidth of the circuit reduces, which would reduce the stability of the high-voltage operational amplifier, and this is the cost of increasing the output current. Generally, the number of parallel circuits is determined by simulation.

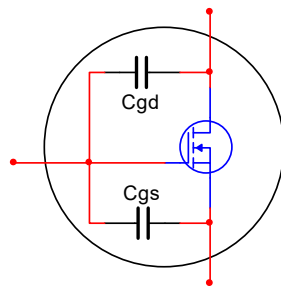


Figure 5. The input capacitance of MOSFETs.

The overall magnification

Based on the analysis of the three stages, the input–output relationship of the proposed high-voltage operational amplifier is described by the Equation (8), where A is the magnification of the proposed high-voltage operational amplifier and A_{1-3} are the magnification of the three stages.

$$V_{out}(t) = A_1 A_2 A_3 (V_{in+}(t) - V_{in-}(t)) = A (V_{in+}(t) - V_{in-}(t)). \quad (8)$$

2.2. The Principles Applying the High-Voltage Operational Amplifier as a Power Amplifier for Piezoelectric Stack Actuators

When applying the high-voltage operational amplifier to form a power amplifier, it is general to use feedback control, so that the magnification of power amplifiers is determined by the feedback

network and the value of the magnification is constant during the designed frequency range. The feedback network is always formed by high-precision resistances and capacitances, which reduces the influence induced by discrete electronic elements of the high-voltage operational amplifiers. There are two methods to use the proposed high-voltage operational amplifier for piezoelectric stack actuator: the noninverting amplifier and the inverting amplifier. The noninverting amplifier used as a power amplifier for piezoelectric stack actuator is shown in Figure 6; it can isolate the input and output well. The transfer function of the circuit can be expressed as follows:

$$F(s) = \frac{A(s)}{1 + A(s)H(s)}. \quad (9)$$

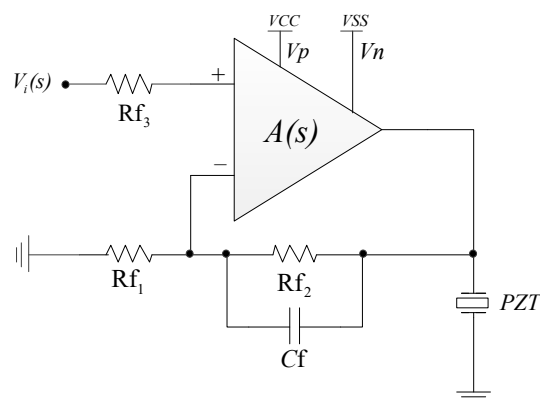


Figure 6. The noninverting amplifier is used as a power amplifier.

In Equation (9), $A(s)$ is the transfer function of the operational amplifier, and $H(s)$ is the transfer function of the feedback network, which is always realized by resistances and capacitances. As long as $A(s)H(s) \gg 1$, Equation (9) can be expressed as follows:

$$F(s) \approx H^{-1}(s). \quad (10)$$

The stability of the power amplifier using feedback control needs to be analyzed and verified by simulations, especially when piezoelectric stack actuators are used as the load.

Considering the noise of circuit as disturbances, the model of the amplifier is shown as Figure 7. In the figure, $N_{1-3}(s)$ are the noise of the input stage, the amplifier stage, and the output stage, respectively, and the influences of the noise can be expressed by Equation (11). According to the equation, the influences of $N_2(s)$ and $N_3(s)$ would be attenuated as $A_1(s) \gg 1$ and $A_2(s) \gg 1$, so that only the noise of the input stage decides the output noise of the circuit. The input stage is composed by low-noise discrete elements, making the output noise of the circuit very low.

$$Y_N(s) = \frac{A(s)N_1(s)}{1+A(s)H(s)} + \frac{A(s)N_2(s)A_1^{-1}(s)}{1+A(s)H(s)} + \frac{A(s)N_3(s)A_1^{-1}(s)A_2^{-1}(s)}{1+A(s)H(s)} \approx H^{-1}(s)N_1(s) + H^{-1}(s)A_1^{-1}(s)N_2(s) + H^{-1}(s)A_1^{-1}(s)A_2^{-1}(s)N_3(s) \quad (11)$$

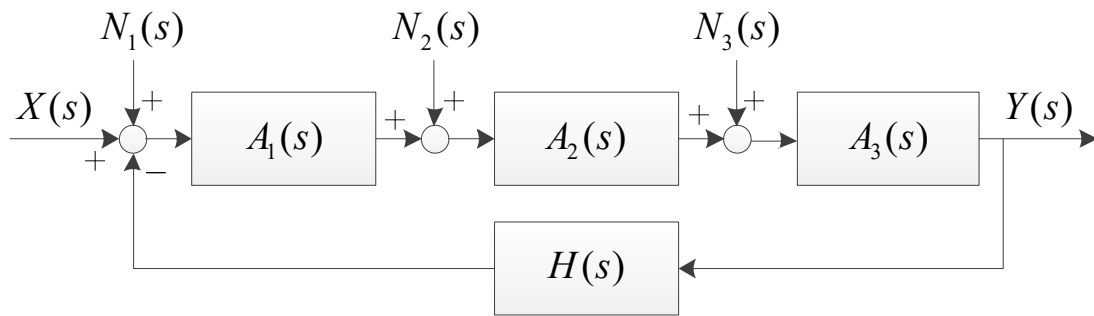


Figure 7. The noise model of the power amplifier.

2.3. The Current Requirements of the Power Amplifiers

Piezoelectric stack actuators have complex electrical and mechanical models [29], and the models have influences on the power amplifier. In general, the model of piezoelectric stack actuators is a capacitor in series with a resistor, which makes the power amplifier need the ability of high output current. In Reference [13], the model of piezoelectric stack actuators is proposed, as shown in Figure 8. As demonstrated in the figure, C_x is the capacitance value of piezoelectric stack actuators, and R_x is the dynamic power loss of piezoelectric stack actuators. The value of C_x is almost several μF , and the value of R_x is several Ohm, and these values can be acquired by impedance analyzer or get from the manufacturer. Taking the model of piezoelectric stack actuators into account, the whole circuit model of the power amplifier and piezoelectric stack actuators is shown in Figure 9. The current $I(s)$ can be expressed as Equation (12):

$$I(s) = \frac{V(s)}{R_s + R_x + L_x s + \frac{1}{C_x s}}, \tag{12}$$

where R_s is the output resistor of the power amplifier, the value is always less than 1Ω , $F(s)$ is the magnification of the power amplifier, and L_x is the inductance of the wire. The value of L_x is generally very small, so that its influence can be neglected. Then the output current $I(s)$ can be expressed as follows:

$$I(s) \approx \frac{V(s)C_x s}{(R_x + R_s)C_x s + 1}. \tag{13}$$

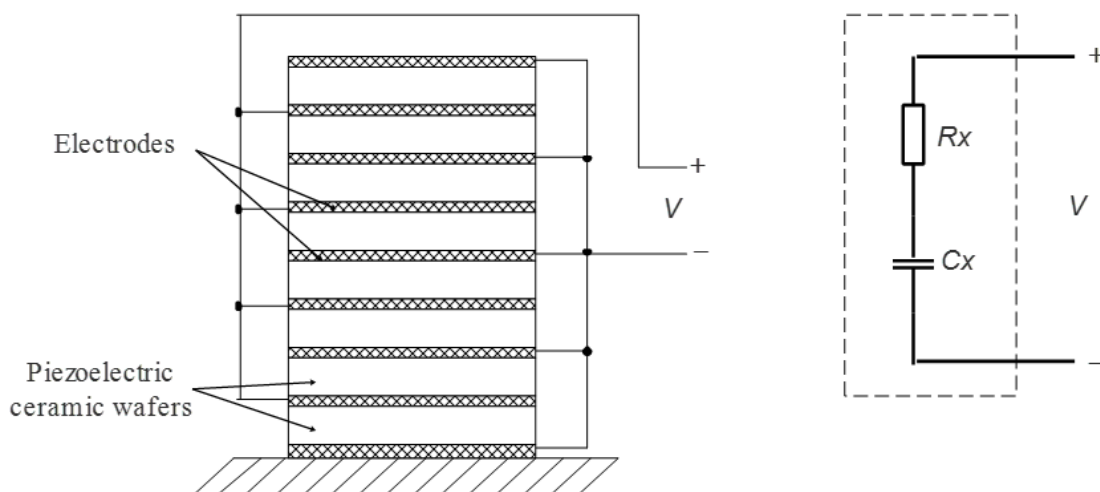


Figure 8. The model of piezoelectric stack actuators.

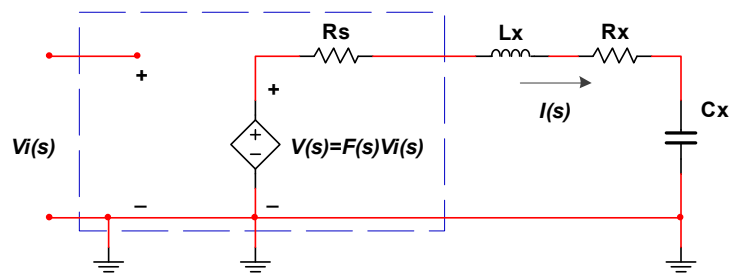


Figure 9. Frequency domain model of the circuit with piezoelectric stack actuators.

When the input signal is explicit, the current of the power amplifier can be calculated by Equation (13), which determines the selection of the electronic elements and the parallel quantity of the current amplification stage of the power amplifier. Periodic sinusoidal tracking is common in the application of piezoelectric stack actuators. In that situation, the out current is calculated easily; let $s = wj$, and Equation (13) can be expressed as follows:

$$I(jw) = \frac{V(jw)C_x jw}{(R_x + R_s)C_x jw + 1}. \quad (14)$$

Let $R = R_x + R_s$ and the amplitude of $V(jw)$ be A . When only amplitude is calculated, the Equation (14) is changed as follows:

$$|I(jw)| = \frac{C_x w}{\sqrt{R^2 C_x^2 w^2 + 1}} |V(jw)| = \frac{A}{\sqrt{R^2 + \frac{1}{C_x^2 w^2}}}. \quad (15)$$

According to Equation (15), the current is determined by the values of the RC and the input frequency when parameter A is determined. As the values of the RC are determined, the current increases by the increasing of the input frequency, and the maximal value of the current is AR^{-1} . Let $w = 2\pi f$ and $A = 100$; as the amplitude of output voltage is 100 V, the relationship between the input frequency and the current as the RC has a different value, as shown in Figure 10. According to Figure 10, the capacitance values of piezoelectric stack actuators and the maximum operating frequency are crucial parameter to design power amplifiers.

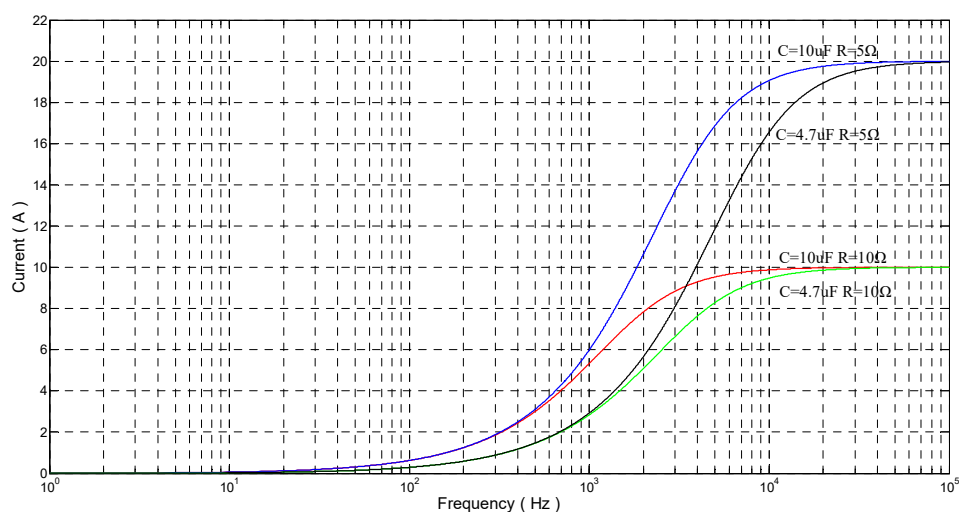


Figure 10. The relationship between current and frequency as the input is sinusoidal wave.

3. Setup of Prototype Circuit Board

In the theoretical analysis of Section 2, the design method of the power amplifier is proposed. Based on different type of piezoelectric stack actuators, it is easy to design the power amplifier by choosing appropriate electronic elements and applying feedback control. In a research of the projection lithography, the requirements are as follows:

1. The piezoelectric stack actuator is P887.51 from Physik Instrumente (Karlsruhe, Germany) [30], whose electrical capacitance is about 3.1 μF .
2. The output voltage range is -100 to $+100$ V, and the magnification is 16 times.
3. The piezoelectric stack actuator works at an operating point; it is needed to track the input signal near the operating point, and the highest moving frequency of the mechanism is less than 100 Hz.
4. The power amplifier, which should be easy to be integrated with the mechanism, must reserve negative voltage for other piezoelectric stack actuators from Physik Instrumente [30], such as P-143.05.

Based on the above requirements, the demanded output current is not large, as the piezoelectric stack actuators do not need to follow the input signal in the full range, so that, in stage 3, the supplied output current is composed by single MOSFETs, and the design could reduce the size of the power amplifier. Taking all the factors into account and referring to the circuit diagram in Figure 1, the results of the design are as follows:

1. In the first and second stage, Q_4 is SSM2212, Q_{2-3} are CZTA44, and Q_1 is FTZ560, while the current source is realized by CPC5603 that is Q_5 or Q_6 in Figure 1. The selection of Q_{1-3} and Q_{5-6} is based on the maximum Collector-Emitter Voltage or the maximum Drain-Source Voltage of these elements. Q_4 is dual-matched NPN transistor whose input noise is low, and SSM2212 matches it well.
2. In the third stage, M_1 and M_2 are IXFR15N100Q3 and IXTH10P60P, which both have more than 45 A instantaneous current and more than 10 A continuous current. The most powers of the MOSFETs are 400 and 460 W, respectively. The selection of M_1 and M_2 is mainly based on V_{DS} and I_D , which are the maximum Drain-Source Voltage and the maximum Drain Current, respectively, and the heat-dissipation performance of these elements should be taken into account.
3. To achieve 16-times magnification, the structure of the noninverting amplifier is used, and the values of resistors are 10 and 150 k, respectively. In order to enhance the stability of the power amplifier, the resistor of 150 k is paralleled with a capacitor of 15 pF.

In order to confirm the effectiveness of design, the simulation of the power amplifier is done in the next section.

4. Simulations and Analysis

4.1. The Simulated Frequency Response of the Power Amplifier

In order to analyze the characteristic of the proposed power amplifier, the simulation of the power amplifier is implemented with the software Cadence 16.6. In the simulation, the positive and negative DC power supplies are set as +110 and -110 V, respectively.

Based on the circuit theory shown by Figure 6 in Section 2, it is convenient to form a power amplifier to drive piezoelectric stack actuators, and the simulated amplitude frequency response of the power amplifier is shown in Figure 11. According to the figure, the following conclusions could be drawn: The power amplifier is stable; the magnification of the power amplifier in the passband is 24.082 dB, which agrees with the theoretical magnification (16 times); the bandwidth is about 68 kHz, and the 0 dB frequency is about 3.5 MHz; and the magnification is flat during the passband of the power amplifier, which is suitable to form a high-precision and highly dynamic piezoelectric positioning system.

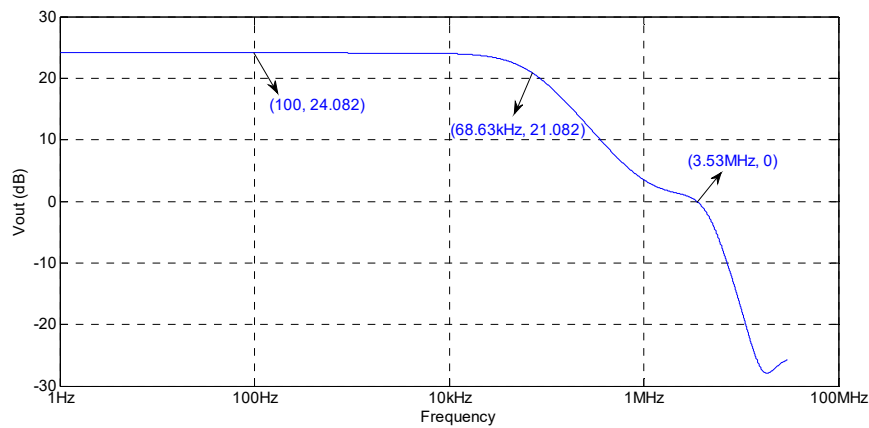


Figure 11. Simulated frequency response of the power amplifier.

4.2. The Simulated Response of the Power Amplifier with Load

The simulated waveform of the power amplifier as sinusoidal input with piezoelectric stack actuators is to verify the ability to respond to the sinusoidal signal. In the simulation, a capacitor of $3.1 \mu\text{F}$ in series with a 10Ω resistor is used to model the piezoelectric stack actuator, as the capacitor of the piezoelectric stack actuator (P887.51) is $3.1 \mu\text{F}$. Using sinusoidal wave with amplitude of 6 V and frequency of 100 Hz as input, which conforms to the working conditions of the power amplifier, the simulated input and output waveforms are shown in Figure 12, the currents of the MOSFETs are shown in Figure 13, and the power consumptions of the MOSFETs are shown in Figure 14. According to the simulated results, the power amplifier has an excellent ability to respond to sinusoidal input, and the current and power consumption are in a safe work area of the MOSFETs.

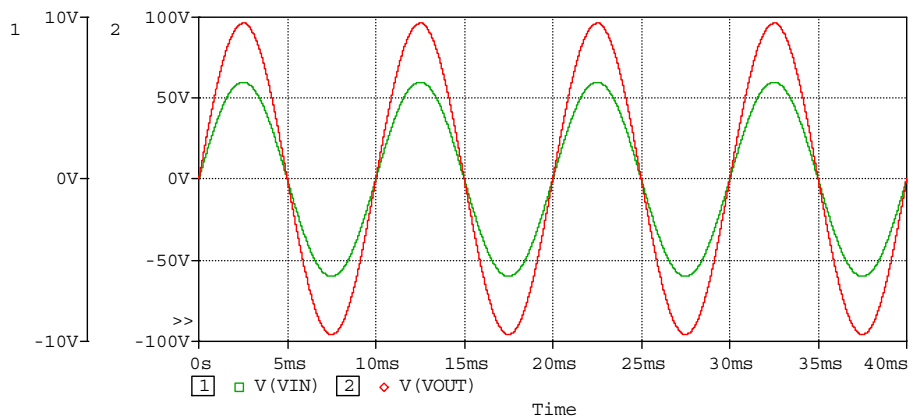


Figure 12. Simulated waveforms of input and output, as the input sinusoidal wave has amplitude of 6 V and frequency of 100 Hz.

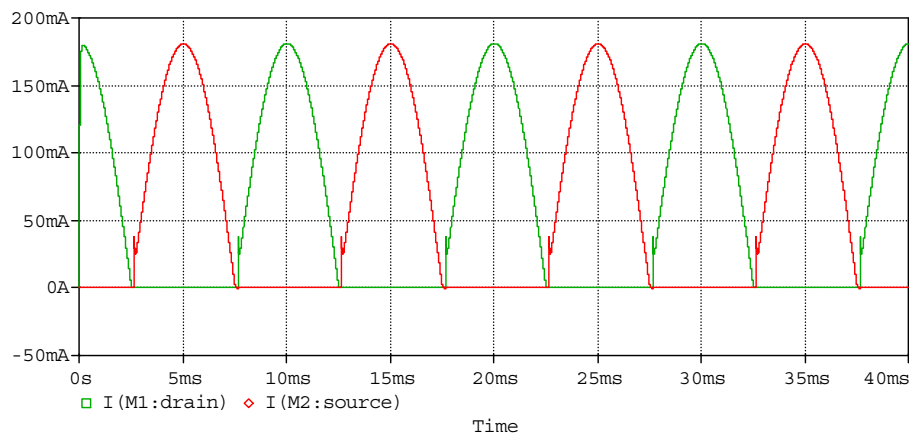


Figure 13. Simulated currents of MOSFETs.

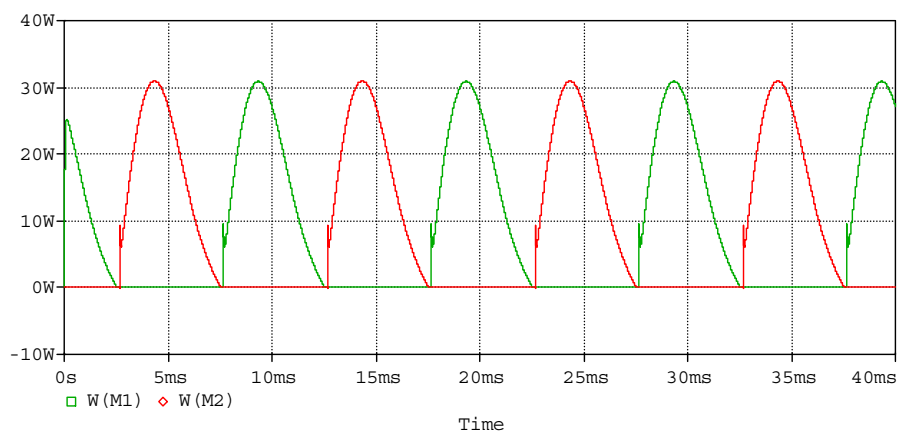
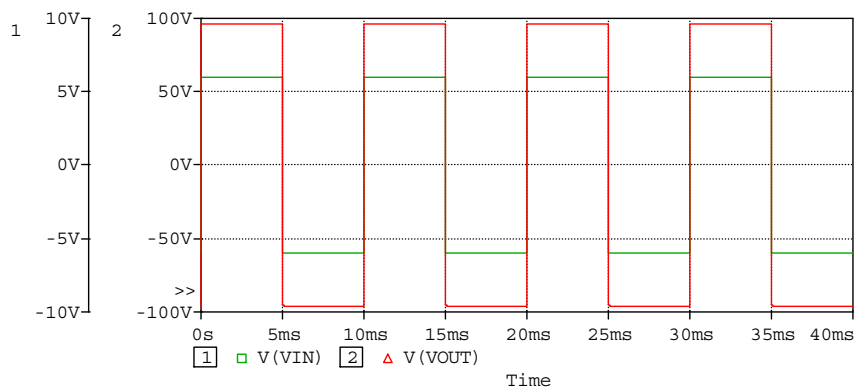


Figure 14. Simulated power consumptions of the MOSFETs.

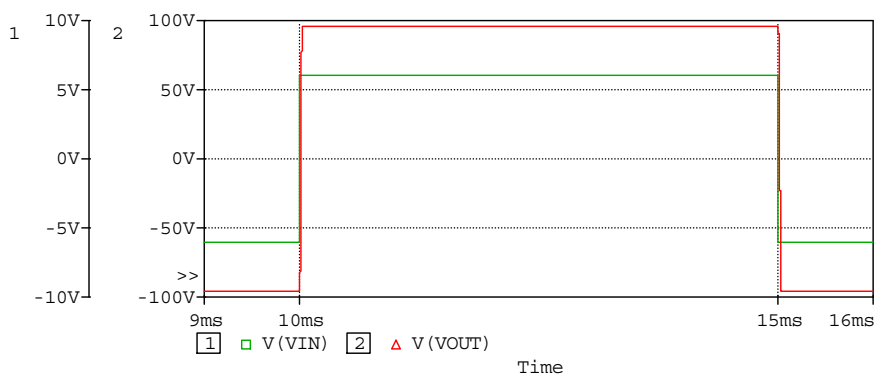
Just as the above setup, the simulated waveforms of the power amplifier as square input are shown in Figures 15–17. The input square wave has the amplitude of 6 V, the frequency of 100 Hz, and the rising time and falling time of 1 μ s. The input and output waveforms of the simulation are shown in Figure 15, which contains the rising and falling edge details. The current of the MOSFETs is shown in Figure 16, and the power consumptions of the MOSFETs are shown in Figure 17. According to the simulated results, the power amplifier has an excellent ability to respond to step input, the most instantaneous currents of the MOSFETs are less than 15 A, and the most instantaneous power consumptions are about 1500 W. The instantaneous currents of the MOSFETs are less than the maximum instantaneous currents of the MOSFETs, which are about 40 A. The instantaneous power consumptions of the MOSFETs are about 1500 W, and the impulse time is about 200 μ s. The average power of the MOSFETs in a period can be expressed by Equation (16):

$$P = P_I \frac{T_I}{T}, \quad (16)$$

where P is the average power, T is the period, P_I is the instantaneous power, and T_I is the instantaneous time. In Equation (16), the instantaneous power is idealized as a narrow pulse. Based on Equation (16), the average power is about 30 W, as the period is 10 ms. The average power of the MOSFETs is less than the maximum powers of the MOSFETs, i.e., 400 and 460 W, respectively. However, the instantaneous power consumptions of the MOSFETs are so big that the MOSFETs should well dissipate heat to avoid damage.



(a)



(b)

Figure 15. Simulated waveforms of input and output, as the input square wave has amplitude of 6 V and frequency of 100 Hz; (a) the overall perspective waveform; and (b) the rising edge and the falling edge of the waveforms.

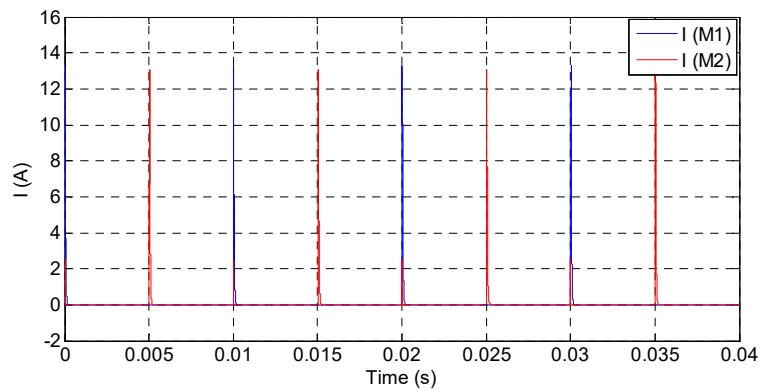


Figure 16. Simulated currents of MOSFETs.

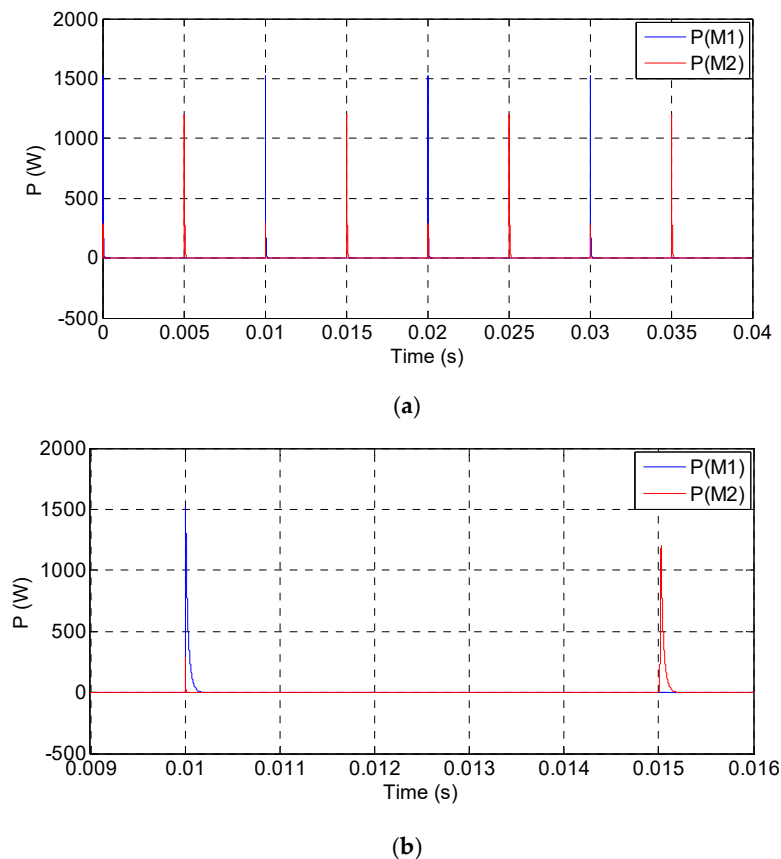


Figure 17. Simulated power consumptions of the MOSFETs: (a) the overall perspective waveform and (b) the detailed power consumptions of M_1 and M_2 .

The simulated results show that the designed power amplifier is consistent with the analysis in Section 2, and the power amplifier is stable and has excellent waveform response. The design results can be further verified by experiments.

5. Experimental Results and Comments

5.1. Experimental Setup

The test setup of the power amplifier is shown in the Figure 18. The main instruments are as follows: The power supply, which is customized from Chaoyang Power Supply Corporation, has the ability of current protection, whose maximum continuous current is 4 A and instantaneous current is 20 A, as the instantaneous time is 2 ms; the waveform generator is 33522B from Keysight Technologies (USA) [31]; the oscilloscopes measuring the waveforms is MSO5204 from Tektronix Corporation (USA) [32]; the multi-meter measuring DC voltage is 34470A form Keysight Technologies [31]; the network analyze testing the system frequency response characteristic is E5061B from Keysight Technologies [31]; and the piezoelectric stack actuator is P887.51 from Physik Instrumente [30].

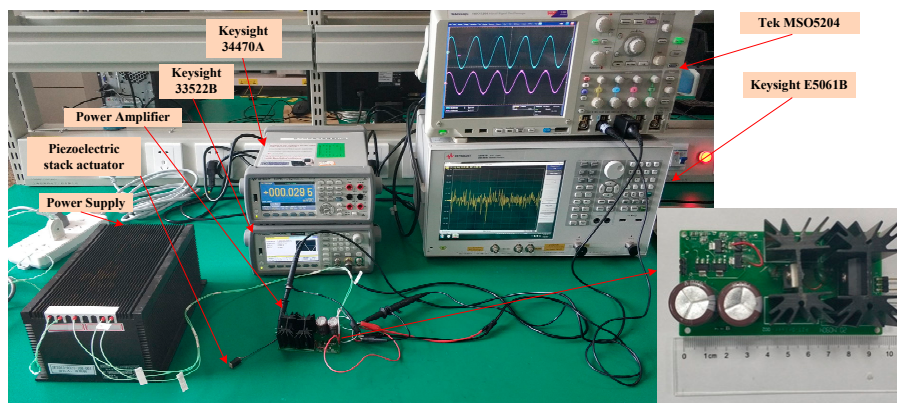


Figure 18. Photograph of the power amplifier's test.

5.2. Frequency–Amplitude Characteristic

The frequency–amplitude characteristic of the power amplifier is shown in Figure 19. According to the figure, the passband gain of the system is 24.026 dB, -3 dB bandwidth is about 57 kHz, and 0 dB bandwidth is about 2.388 MHz. The overall shape of the frequency–amplitude characteristics is consistent with the results of simulation analysis; there are a few differences between the tested frequency and the simulated frequency at the key frequency points, but the differences are not significant. The reasons for the differences are that the simulation uses an ideal electronic elements model which could not be found, and the simulation does not consider the distributed parameter of the print circuit board. As the differences are slight, especially in the low-frequency range, the simulation results can be used as references in the design.

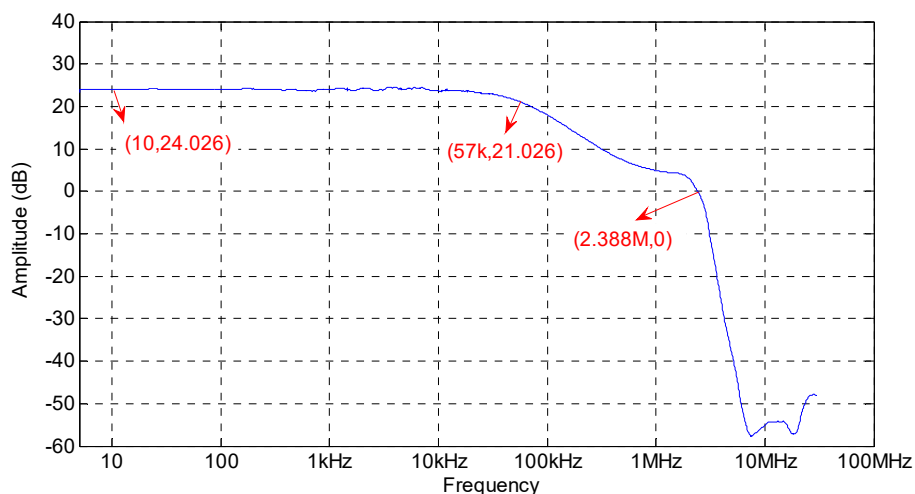


Figure 19. Measured frequency–amplitude characteristic.

5.3. The Ripple of the Power Amplifier

The out ripple is the important performance of various power amplifiers. As to the linear power supply, such as the designed power amplifier, the ripple is the output noise. The output ripple of the power amplifier would influence the output displacement accuracy of the piezoelectric stack actuator, especially in high-precision applications. Oscilloscope MSO5204 from Tektronix Corporation [32] was used for ripple test, with P2221 from Tektronix Corporation [32] as probe. We connected the input to ground, and the achieved output ripple is shown in Figure 20. According to the figure, the ripple of the power amplifier is less than 2 mV.

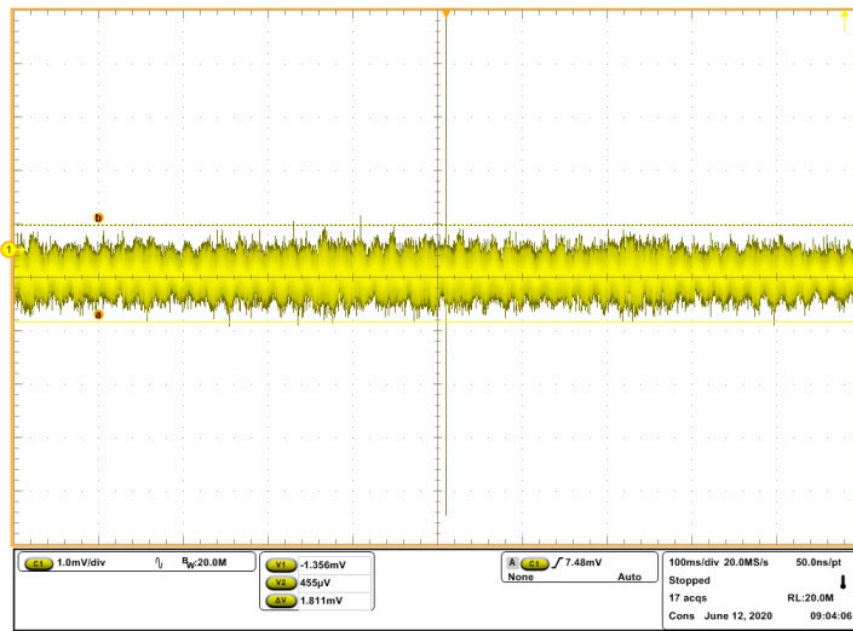


Figure 20. Measured ripple of the power amplifier.

5.4. Tests with Piezoelectric Stack Actuator

In order to verify the stability of the power amplifier, a piezoelectric stack actuator (P887.51) is connected to the power amplifier. Using 100 Hz sinusoidal wave or 100 Hz square wave whose amplitude are both 6 V as input, respectively, the responses are shown in Figures 21 and 22, which agree with the simulation results. The reason of choosing 100 Hz as the frequency point is that the highest moving frequency of the mechanism is 100 Hz.

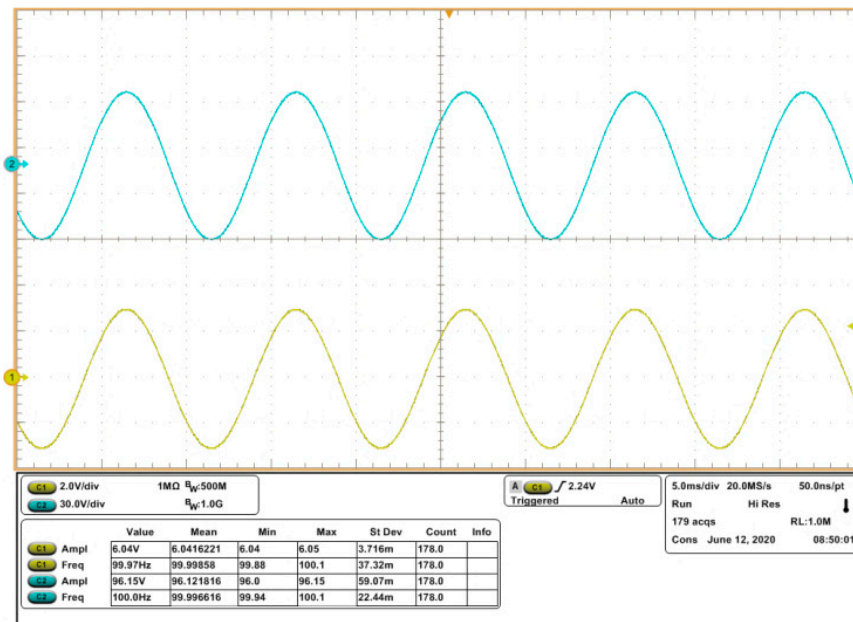


Figure 21. Measured waveforms of input (c1) and output (c2), as the input sinusoidal wave has an amplitude of 6 V and frequency of 100 Hz.

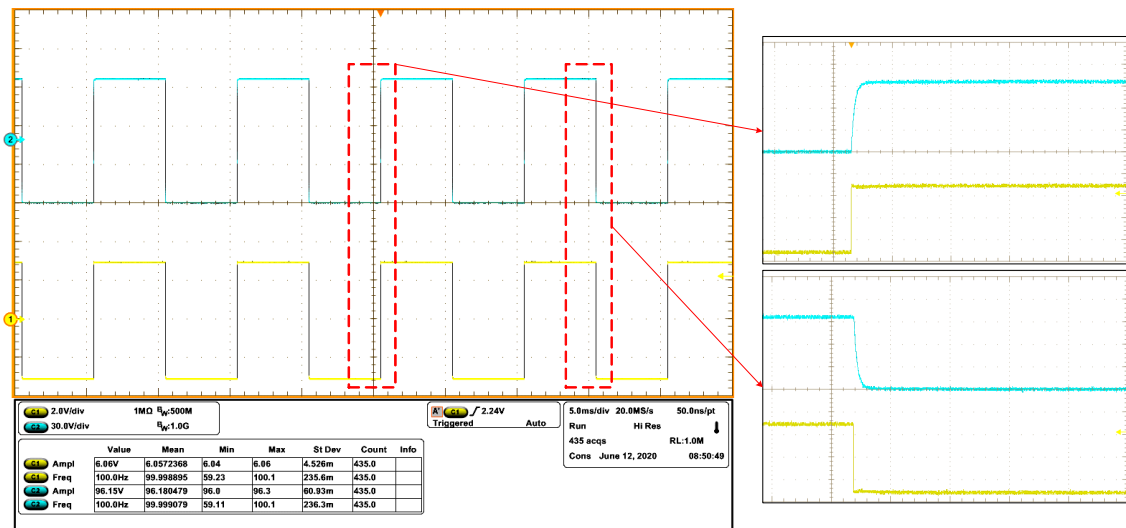


Figure 22. Measured waveforms of input (c1) and output (c2), as the input square wave has amplitude of 6 V and frequency of 100 Hz.

5.5. Tests in the System

The mechanical stage for which the piezoelectric stacks actuator (P887.51) is applied is shown in Figure 23. The mechanical stage of 1 degree of freedom has a nominal displacement of 0–12 μm, which can be measured by Heidenhain LIP281 integrated in the stage. The stage is used to move required displacement and do some local adjustments at the position, and it is electrically excited by the designed power amplifier. The power amplifier uses the waveform generator (Keysight 33522B) to produce the input signal, and the power amplifier is powered by the customized power supply. The laboratory is under precise environmental control, with its ambient temperature kept at 22 ± 0.2 °C.

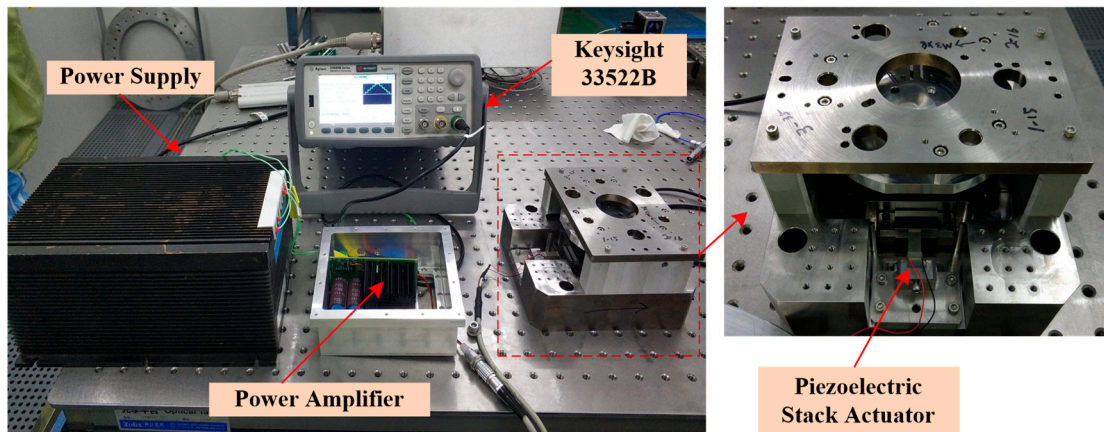
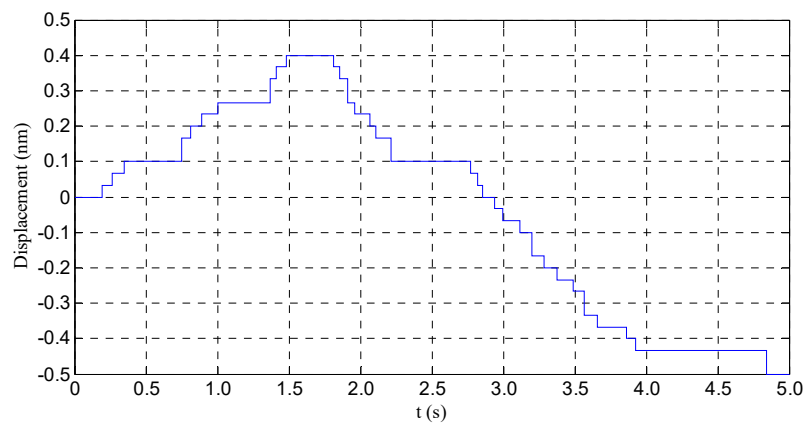
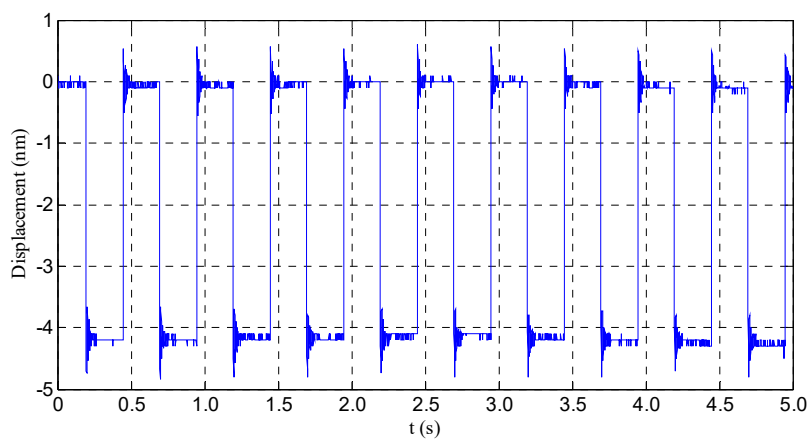


Figure 23. The setup of the tests in the system.

The noise of the used displacement sensor is shown in Figure 24a. According to the figure, the noise of the sensor is about 1 nm. The resolution of the mechanical stage is shown in Figure 24b, as the input signal is a square wave whose period and amplitude are 500 ms and 3 mV, respectively. According to Figure 24, the resolution of the mechanism is about 4.5 nm. The input–output relationship of the mechanical stage is shown in Figure 25; the step voltage and the step time of the input signal are 1.2 V and 200 ms, respectively. According to Figure 25, the output step displacement is about 2.5 μm, and the rise and fall characteristics are not consistent, due to the hysteresis effect of the piezoelectric stacks actuator. All of these results show that the designed power amplifier has excellent performances to drive the piezoelectric stacks actuator.

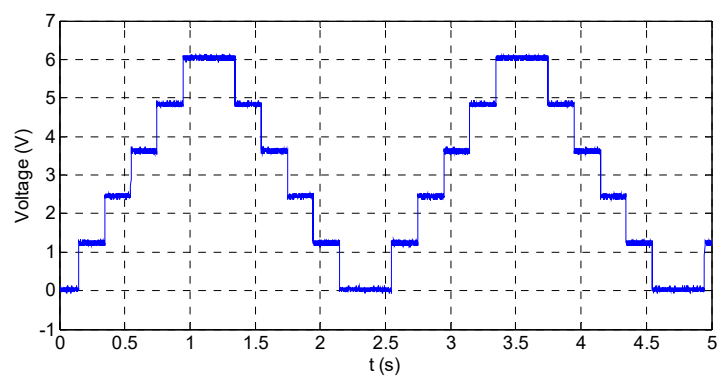


(a)



(b)

Figure 24. The output displacement resolution of the mechanism: (a) the noise of the sensor, and (b) the output displacement resolution of the mechanism.



(a)

Figure 25. Cont.

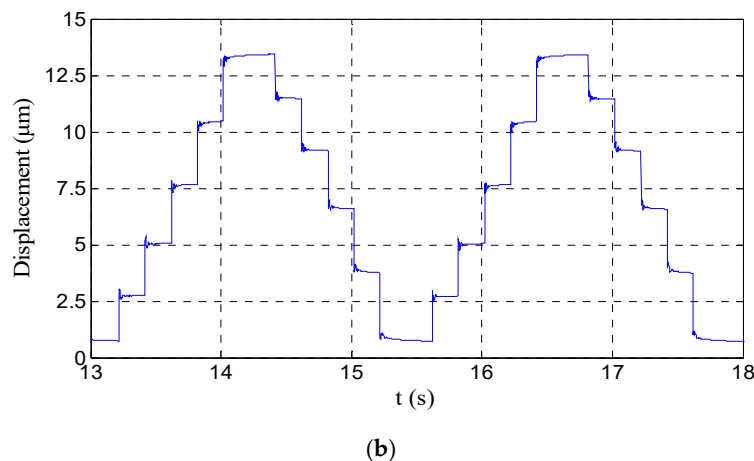


Figure 25. Measured input–output relationship of the mechanical stage: (a) the input voltage signal, and (b) the output displacement of the mechanical stage.

5.6. Comparisons

The comparisons between the proposed power amplifier and some existing power amplifier are listed in Table 1, and the comparisons are carried out as the power amplifiers are without load. According to the table, the designed power amplifier has the advantages of low noise, small size, and low price. However, every coin has two sides; the design involves much work on the selection of the electronic elements, which increases the difficulty of design. As the paper discussed the principles of the circuit thoroughly in Section 2, the adverse factors in the design are minimized.

Table 1. Comparisons between the proposed power amplifier and some existing power amplifiers.

References	Ripple	Bandwidth	Price	Size
[13]	20 mV	About 20 kHz	Medium	Big
[15]	Not give	20 kHz	Medium	Medium
[25]	40 mV	Not give	Low	Medium
E-618 (Physik Instrumente [30])	20 mV	About 15 kHz	High	Big
This work	2 mV	57 kHz	Low	Small

6. Conclusions

In this article, aiming at low cost, small size, and high precision, a power amplifier which conforms to the design principles of general operational amplifier is explored. Based on the theory of general operational amplifiers, the circuit structure of the power amplifier is proposed, and the method of applying the proposed amplifier to form a piezoelectric driver is described. The unique design requirements produced piezoelectric stack actuators, which are similar to the series connection of capacitance and resistance, were analyzed. In a precision positioning application, using P887.51 from Physik Instrumente [30], core electronic elements were selected. Using the PSPICE models of the elements, the designed circuit was simulated and confirmed to meet the requirements. Then, by testing a prototype circuit, experimental data and curves were achieved, and the experimental results are consistent with the simulation results perfectly. The experimental results demonstrate that the bandwidth of the power amplifier is about 57 kHz, the output ripple is less than 2 mV, the displacement resolution of the mechanical stage which the power amplifier is applied in is about 4.5 nm, and the proposed power amplifier can well driver the piezoelectric stack actuator during the travel range of the mechanical stage.

Author Contributions: L.X., methodology, investigation, experiment data analysis, and writing—original draft, review and editing; H.L., supervision and funding acquisition; P.L., conceptualization; C.G., conceptualization. All authors have read and agreed to the published version of the manuscript.

Funding: This work was supported in part by the National Science and Technology Major Project of China (Grant No. 2009ZX02205).

Conflicts of Interest: The authors declared no conflict of interest.

References

1. Goldfarb, M.; Celanovic, N. Modeling piezoelectric stack actuators for control of micromanipulation. *IEEE Control. Syst.* **1997**, *17*, 69–79.
2. Gnad, G.; Kasper, R. A power drive control for piezoelectric actuators. *2004 IEEE Int. Symp. Ind. Electron.* **2004**, *2*, 963–967.
3. Porfiri, M.; Dell’Isola, F.; Mascioli, F.M.F. Circuit analog of a beam and its application to multimodal vibration damping, using piezoelectric transducers. *Int. J. Circuit Theory Appl.* **2004**, *32*, 167–198. [[CrossRef](#)]
4. Gift, S.J.G.; Maundy, B.J. A novel circuit element and its application in signal amplification. *Int. J. Circuit Theory Appl.* **2008**, *36*, 219–231. [[CrossRef](#)]
5. Shao, Y.; Xu, M.; Shao, S.; Song, S. Effective dynamical model for piezoelectric stick–slip actuators in bi-directional motion. *Mech. Syst. Signal Process.* **2020**, *145*, 106964. [[CrossRef](#)]
6. Deng, J.; Chen, W.; Li, K.; Wang, L.; Liu, Y. A sandwich piezoelectric actuator with long stroke and nanometer resolution by the hybrid of two actuation modes. *Sens. Actuators A Phys.* **2019**, *296*, 121–131. [[CrossRef](#)]
7. Xu, Z.; Huang, H.; Dong, J. A stick-slip piezoelectric actuator with measurable contact force. *Mech. Syst. Signal Process.* **2020**, *144*, 106881. [[CrossRef](#)]
8. Peng, T.; Dai, C.; Lou, J.; Cui, Y.; Tao, B.; Ma, J. A low-cost deformable lens for correction of low-order aberrations. *Opt. Commun.* **2020**, *460*, 125209. [[CrossRef](#)]
9. Comstock, R.H. Charge Control of Piezoelectric Actuators to Reduce Hysteresis Effects. U.S. Patent 4,263,527, 21 April 1981.
10. Yang, C.; Li, C.; Xia, F.; Zhu, Y.; Zhao, J.; Youcef-Toumi, K. Charge controller with decoupled and self-compensating configurations for linear operation of piezoelectric actuators in a wide bandwidth. *IEEE Trans. Ind. Electron.* **2018**, *66*, 5392–5402. [[CrossRef](#)]
11. Rios, S.; Fleming, A.J. Design of a charge drive for reducing hysteresis in a piezoelectric bimorph actuator. *IEEE/ASME Trans. Mechatron.* **2015**, *21*, 51–54. [[CrossRef](#)]
12. Yang, C.; Li, C.; Zhao, J. A nonlinear charge controller with tunable precision for highly linear operation of piezoelectric stack actuators. *IEEE Trans. Ind. Electron.* **2017**, *64*, 8618–8625. [[CrossRef](#)]
13. Wang, D.H.; Zhu, W.; Yang, Q.; Ding, W. A high-voltage and high-power amplifier for driving piezoelectric stack actuators. *J. Intell. Mater. Syst. Struct.* **2009**, *20*, 1987–2001. [[CrossRef](#)]
14. Wallenhauer, C.; Gottlieb, B.; Zeichfusl, R.; Kappel, A. Efficiency-improved high-voltage analog power amplifier for driving piezoelectric actuators. *IEEE Trans. Circuits Syst. I Regul. Pap.* **2009**, *57*, 291–298. [[CrossRef](#)]
15. Milecki, A.; Regulski, R. Investigations of electronic amplifiers supplying a piezobimorph actuator. *Mech. Syst. Signal Process.* **2016**, *78*, 43–54. [[CrossRef](#)]
16. Antonio, J.L.M.; Lucia, A.; Coro, G.A.; Ramon, G.C.; Jaime, R.A. Power-efficient analog design based on the class AB super source follower. *Int. J. Circuit Theory Appl.* **2012**, *40*, 1143–1163.
17. Chiu, H.-J.; Lo, Y.-K.; Chang, Y.-C.; Tseng, P.-J.; Liu, Y.-C. High-voltage power amplifier for flexible paper speaker applications. *Int. J. Circuit Theory Appl.* **2012**, *42*, 165–172. [[CrossRef](#)]
18. Rautio, T.; Harju, H.; Hietakangas, S.; Rahkonen, T. Envelope tracking power amplifier with static predistortion linearization. *Int. J. Circuit Theory Appl.* **2009**, *37*, 365–375. [[CrossRef](#)]
19. Chen, W.; Floberg, H.; Qiu, S.-S. A new analytical method for analysis and design of Class E power amplifiers taking into account the switching device on resistance. *Int. J. Circuit Theory Appl.* **1999**, *27*, 421–436. [[CrossRef](#)]
20. Wallenhauer, C.; Kappel, A.; Gottlieb, B.; Schwebel, T.; Lüth, T. Efficient class-B analog amplifier for a piezoelectric actuator drive. *Mechatronics* **2009**, *19*, 56–64. [[CrossRef](#)]
21. Jeng, S.-L.; Tung, Y.-C. A multicell linear power amplifier for driving piezoelectric loads. *IEEE Trans. Ind. Electron.* **2008**, *55*, 3644–3652. [[CrossRef](#)]
22. Walker, G. A Class B switch-mode assisted linear amplifier. *IEEE Trans. Power Electron.* **2003**, *18*, 1278–1285. [[CrossRef](#)]

23. Ertl, H.; Kolar, J.; Zach, F. Basic considerations and topologies of switched-mode assisted linear power amplifiers. *IEEE Trans. Ind. Electron.* **1997**, *44*, 116–123. [[CrossRef](#)]
24. Mansour, S.Z.; Seethaler, R.J. Simultaneous displacement and force estimation of piezoelectric stack actuators using charge and voltage measurements. *IEEE/ASME Trans. Mechatron.* **2017**, *22*, 2619–2624. [[CrossRef](#)]
25. Lin, C.-Y.; Tampubolon, M.; Lo, Y.-K.; Lin, J.-Y.; Wu, Y.-C.; Chiu, H.-J. Study and implementation of a 15-W driver for piezoelectric actuators. *Int. J. Circuit Theory Appl.* **2016**, *45*, 439–454. [[CrossRef](#)]
26. Fleming, A.J. A megahertz bandwidth dual amplifier for driving piezoelectric actuators and other highly capacitive loads. *Rev. Sci. Instrum.* **2009**, *80*, 104701. [[CrossRef](#)]
27. Tung, Y.-C.; Jeng, S.-L.; Chieng, W.-H. Multi-level balanced isolated floating difference amplifier. *IEEE Trans. Circuits Syst. I Regul. Pap.* **2008**, *55*, 3016–3022. [[CrossRef](#)]
28. Apex Microtechnology. Available online: <https://www.apexanalog.com> (accessed on 23 June 2020).
29. Yao, K.; Uchino, K.; Xu, Y.; Dong, S.; Lim, L.C. Compact piezoelectric stacked actuators for high power applications. *IEEE Trans. Ultrason. Ferroelectr. Freq. Control.* **2000**, *47*, 819–825.
30. Physik Instrumente. Available online: <https://www.physikinstrumente.com> (accessed on 23 June 2020).
31. Keysight Technologies. Available online: <https://www.keysight.com> (accessed on 23 June 2020).
32. Tektronix Corporation. Available online: <https://www.tek.com.cn> (accessed on 23 June 2020).

Publisher’s Note: MDPI stays neutral with regard to jurisdictional claims in published maps and institutional affiliations.



© 2020 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (<http://creativecommons.org/licenses/by/4.0/>).