

Fixed Point Problems on Generalized Metric Spaces in Perov's Sense

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Abstract: The aim of this paper is to give some fixed point results in generalized metric spaces in Perov's sense. The generalized metric considered here is the w -distance with a symmetry condition. The operators satisfy a contractive weakly condition of Hardy–Rogers type. The second part of the paper is devoted to the study of the data dependence, the well-posedness, and the Ulam–Hyers stability of the fixed point problem. An example is also given to sustain the presented results.

Keywords: fixed point; coupled fixed points; Perov space; generalized w -distance; Ulam–Hyers stability; well-posedness; data dependence

1. Introduction and Preliminaries

The well-known Banach contraction principle was extended by Perov in 1964 to the case of spaces endowed with vector-valued metrics. In [1], Perov introduced the concept of vector-valued metric as follows.

Let X be a nonempty set. A mapping $\tilde{d} : X \times X \rightarrow \mathbb{R}^m$ where $\tilde{d} = \begin{pmatrix} d_1(x, y) \\ \dots \\ d_m(x, y) \end{pmatrix}$ for every $m \in \mathbb{N}$

is called vector-valued metric on X if the following properties are satisfied.

- (1) $\tilde{d}(x, y) \geq 0$ for all $x, y \in X$, and $\tilde{d}(x, y) = 0$ implies $x = y$;
- (2) $\tilde{d}(x, y) = \tilde{d}(y, x)$;
- (3) $\tilde{d}(x, y) \leq \tilde{d}(x, z) + \tilde{d}(z, y)$ for all $x, y, z \in X$.

In this case, the pair (X, \tilde{d}) is called a generalized metric space in Perov's sense. Some examples of fixed points on the sense of vector-valued metric are given in [2–6]. Throughout this paper $\mathcal{M}_{m,m}(\mathbb{R}_+)$ will denote the set of all $m \times m$ matrices with positive elements. We also denote by Θ the zero $m \times m$

matrix and $0_{1 \times m} = \begin{pmatrix} 0 \\ \dots \\ 0 \end{pmatrix}$, by I the identity $m \times m$ matrix and $I_{1 \times m} = \begin{pmatrix} 1 \\ \dots \\ 0 \end{pmatrix}$ and by U the unity

$m \times m$ matrix and $U_{1 \times m} = \begin{pmatrix} 1 \\ \dots \\ 1 \end{pmatrix}$. If $A \in \mathcal{M}_{m,m}(\mathbb{R}_+)$, then the symbol A^τ stands for the transpose matrix of A .

Recall that a matrix A is said to be convergent to zero if and only if $A^n \rightarrow \Theta$ as $n \rightarrow \infty$.

Let us recall the following theorem, which is useful for the proof of the main result, see [7].

Theorem 1. Let $A \in \mathcal{M}_{m,m}(\mathbb{R}_+)$. The following assertions are equivalent.

- (i) A is a matrix convergent to zero;
- (ii) $A^n \rightarrow \mathbf{0}$ as $n \rightarrow \infty$;
- (iii) The eigenvalues of A are in the open unit disc, i.e., $|\lambda| < 1$, for each $\lambda \in \mathbb{C}$ with $\det(A - \lambda I) = 0$;
- (iv) The matrix $I - A$ is non-singular and

$$(I - A)^{-1} = I + A + \dots + A^n + \dots;$$

- (v) The matrix $I - A$ is non-singular and the matrix $(I - A)^{-1}$ has nonnegative elements.

In [8], one can find that the notion of K-metric, which is an extension of the Perov's metric. Huang and Zhang reconsidered in [9] the notion of K-metric under the name *cone metric*.

Hardy and Rogers [10] proved in 1973 a generalization of Reich fixed point theorem. Having this as a starting point, many authors obtained fixed point results for Hardy–Rogers type operators.

Let (X, d) be a metric space. Throughout this paper we use the following notations.

$P(X)$: the set of all nonempty subsets of X ;

$P_{cl}(X)$: the set of all nonempty closed subsets of X ;

$P_{cp}(X)$: the set of all nonempty compact subsets of X ;

$Fix(F) := \{x \in X \mid x \in F(x)\}$: the set of the fixed points of F ;

$SFix(F) := \{x \in X \mid \{x\} = F(x)\}$: the set of the strict fixed points of F .

We denote by \mathbb{N} the set of all natural numbers. We also denote by $\mathbb{N}^* := \mathbb{N} - \{0\}$ the set of all natural numbers without 0.

Let (X, \tilde{d}) be a generalized metric space in the sense of Perov. Here, if $v, r \in \mathbb{R}^m$ have the form $v := (v_1, v_2, \dots, v_m)$ and $r := (r_1, r_2, \dots, r_m)$, then by the inequality $v \leq r$ we mean $v_i \leq r_i$, for each $i \in \{1, 2, \dots, m\}$, whereas by the inequality $v < r$, we mean $v_i < r_i$, for each $i \in \{1, 2, \dots, m\}$. Moreover, $|v| := (|v_1|, |v_2|, \dots, |v_m|)$ and, if $c \in \mathbb{R}$ then $v \leq c$ means $v_i \leq c$, for each $i \in \{1, 2, \dots, m\}$.

We can notice that, in a generalized metric space, some concepts are similar to those given for metric space. Some of these concepts are Cauchy sequence, convergent sequence, completeness, and open and closed subsets.

In [11], Kada et al. introduced the concept of w -distance and improved several results replacing the involved metric by a generalized distance. On the other hand, the notions of single-valued and multivalued weakly contractive maps with respect to w -distance was introduced by Suzuki and Takahashi in [12]. Some recent fixed point results involving the w -distance can be found in [12–19].

Definition 1. A mapping $w : X \times X \rightarrow [0, \infty)$ is a w -distance on X if it satisfies the following conditions for any $x, y, z \in X$.

- (1) $w(x, z) \leq w(x, y) + w(y, z)$;
- (2) the function $w(x, \cdot) : X \rightarrow [0, \infty)$ is lower semicontinuous;
- (3) for any $\varepsilon > 0$, there exists $\delta > 0$ such that $w(z, x) \leq \delta$ and $w(z, y) \leq \delta$ imply $d(x, y) \leq \varepsilon$.

In [20], we find the definition of w_0 -distance as follows.

Definition 2. Let (X, d) be a metric space. A mapping $w : X \times X \rightarrow [0, \infty)$ is called w_0 -distance if it is w -distance on X with $w(x, x) = 0$ for every $x \in \mathbb{R}$.

Remark 1. Each metric is a \tilde{w}_0 -distance, but the reverse is not true.

For the following notations see I.A. Rus [21,22], I.A. Rus, A. Petruşel, A. Sintămărian [23], and A. Petruşel [24].

Definition 3. Let (X,d) be a metric space and $f : X \rightarrow X$ be a single-valued operator. f is a weakly Picard operator (briefly WPO) if the sequence of successive approximations for f starting from $x \in X$, $(f^n(x))_{n \in \mathbb{N}}$, converges, for all $x \in X$ and its limit is a fixed point for f .

If f is a WPO, then we consider the operator

$$f^\infty : X \rightarrow X \text{ defined by } f^\infty(x) := \lim_{n \rightarrow \infty} f^n(x).$$

Notice that $f^\infty(X) = \text{Fix}(f)$.

Definition 4. Let (X,d) be a metric space, $f : X \rightarrow X$ be a WPO and $c > 0$ be a real number. By definition, the single-valued operator f is c -weakly Picard operator (briefly c -WPO) if and only if the following inequality holds,

$$d(x, f^\infty(x)) \leq cd(x, f(x)), \text{ for all } x \in X.$$

For the theory of weakly Picard operators, for single-valued operators, see [21].

I.A. Rus gave in [22] the definition of Ulam–Hyers stability as follows.

Definition 5. Let (X,d) be a metric space and $f : X \rightarrow X$ be a single-valued operator. By definition, the fixed point equation

$$x = f(x) \tag{1}$$

is Ulam–Hyers stable if there exists a real number $c_f > 0$ such that for each $\varepsilon > 0$ and each solution y^* of the inequation

$$d(y, f(y)) \leq \varepsilon \tag{2}$$

there exists a solution x^* of Equation (1) such that

$$d(y^*, x^*) \leq c_f \varepsilon.$$

Remark 2. If f is a c -weakly Picard operator, then the fixed point Equation (1) is Ulam–Hyers stable.

The Ulam stability of different functional type equations have been investigated by many authors (see [25–35]).

We present in the first part of this paper some fixed point results in generalized metric spaces in Perov’s sense. The operator satisfies a contractive condition of Hardy–Rogers type. In the second part of the paper, we study the data dependence of the fixed point set. The well-posedness of the fixed point problem and the Ulam–Hyers stability are also studied.

2. Fixed Point Results

First, let us we recall the notion of generalized w -distance defined in [36] by L. Guran.

Definition 6. Let (X, \tilde{d}) be a generalized metric space. The mapping $\tilde{w} : X \times X \rightarrow \mathbb{R}_+^m$ is called generalized w -distance on X if it satisfies the following conditions.

- (1) $\tilde{w}(x, y) \leq \tilde{w}(x, z) + \tilde{w}(z, y)$, for every $x, y, z \in X$;
- (2) \tilde{w} is lower semicontinuous with respect to the second variable.;
- (3) For any $\varepsilon := \begin{pmatrix} \varepsilon_1 \\ \dots \\ \varepsilon_m \end{pmatrix} > 0$, there exists $\delta := \begin{pmatrix} \delta_1 \\ \dots \\ \delta_m \end{pmatrix} > 0$, such that $\tilde{w}(z, x) \leq \delta$ and $\tilde{w}(z, y) \leq \delta$ implies $\tilde{d}(x, y) \leq \varepsilon$.

Examples of generalized w -distance and some of its useful properties are also given in [36] and [37]. In the same framework, let us give the definition of generalized w_0 -distance.

Definition 7. Let (X, \tilde{d}) be a generalized metric space. A mapping $\tilde{w} : X \times X \rightarrow [0, \infty)$ is called generalized \tilde{w}_0 -distance if it is generalized w -distance on X with $\tilde{w}(x, x) = 0_{1 \times m}$ for every $x \in X$.

Let us recall the following useful result.

Lemma 1. Let (X, \tilde{d}) be a generalized metric space, and let $\tilde{w} : X \times X \rightarrow \mathbb{R}_+^m$ be a generalized w -distance on X . Let (x_n) and (y_n) be two sequences in X , let $\alpha_n := \begin{pmatrix} \alpha_{n1} \\ \dots \\ \alpha_{nm} \end{pmatrix} \in \mathbb{R}_+^m$ and $\beta_n = \begin{pmatrix} \beta_{n1} \\ \dots \\ \beta_{nm} \end{pmatrix} \in \mathbb{R}_+^m$ be two sequences such that $\alpha_{n(i)}$ and $\beta_{n(i)}$ converge to zero for each $i \in \{1, 2, \dots, m\}$. Let $x, y, z \in X$. Then, the following assertions hold, for every $x, y, z \in X$.

- (1) If $\tilde{w}(x_n, y) \leq \alpha_n$ and $\tilde{w}(x_n, z) \leq \beta_n$ for any $n \in \mathbb{N}$, then $y = z$.
- (2) If $\tilde{w}(x_n, y_n) \leq \alpha_n$ and $\tilde{w}(x_n, z) \leq \beta_n$ for any $n \in \mathbb{N}$, then (y_n) converges to z .
- (3) If $\tilde{w}(x_n, x_m) \leq \alpha_n$ for any $n, m \in \mathbb{N}$ with $m > n$, then (x_n) is a Cauchy sequence.
- (4) If $\tilde{w}(y, x_n) \leq \alpha_n$ for any $n \in \mathbb{N}$, then (x_n) is a Cauchy sequence.

Next, let us give the definition of single-valued weakly Hardy–Rogers type operator on generalized metric space in Perov’s sense.

Definition 8. Let (X, \tilde{d}) be a generalized metric space in Perov’s sense, $\tilde{w} : X \times X \rightarrow \mathbb{R}_+^m$ be a generalized w -distance, and $f : X \rightarrow X$ be a single-valued operator. We say that f is a weakly Hardy–Rogers type operator if the following inequality is satisfied,

$$\tilde{w}(f(x), f(y)) \leq A\tilde{w}(x, y) + B[\tilde{w}(x, f(x)) + \tilde{w}(y, f(y))] + C[\tilde{w}(x, f(y)) + \tilde{w}(y, f(x))],$$

for all $x, y \in X$ and $A, B, C \in \mathcal{M}_{m,m}(\mathbb{R}_+)$.

The first fixed point result of this paper is the following.

Theorem 2. Let (X, \tilde{d}) be a complete generalized metric space in Perov’s sense, $\tilde{w} : X \times X \rightarrow \mathbb{R}_+^m$ be a generalized w_0 -distance. Let $f : X \rightarrow X$ be a single-valued weakly Hardy–Rogers type operator such that

- (a) f is continuous;
- (b) there exist matrices $A, B, C \in \mathcal{M}_{m,m}(\mathbb{R}_+)$ such that

- (i) $M = (I - (B + C))^{-1}(A + B + C)$ converges to Θ ;
- (ii) $I - (B + C)$ is nonsingular and $(I - (B + C))^{-1} \in \mathcal{M}_{m,m}(\mathbb{R}_+)$;
- (iii) $I - (A + 2B + 2C)$ is nonsingular and $[I - (A + 2B + 2C)]^{-1} \in \mathcal{M}_{m,m}(\mathbb{R}_+)$.

Then, $\text{Fix}(f) \neq \emptyset$. Moreover, if $x^* = f(x^*)$, then $w(x^*, x^*) = 0$.

Proof. Fix $x_0 \in X$. Let $x_1 = f(x_0)$ and $x_2 = f(x_1)$. Then, we have

$$\begin{aligned} \tilde{w}(x_1, x_2) &= \tilde{w}(f(x_0), f(x_1))A\tilde{w}(x_0, x_1) + B[\tilde{w}(x_0, f(x_0)) + \tilde{w}(x_1, f(x_1))] + C[\tilde{w}(x_0, f(x_1)) \\ &+ \tilde{w}(x_1, f(x_0))] = A\tilde{w}(x_0, x_1) + B[\tilde{w}(x_0, x_1) + \tilde{w}(x_1, x_2)] + C[\tilde{w}(x_0, x_2) + \tilde{w}(x_1, x_1)] \\ &= (A + B)\tilde{w}(x_0, x_1) + B(\tilde{w}(x_1, x_2)) + C[\tilde{w}(x_0, x_2) + \tilde{w}(x_1, x_2)] \\ &= (A + B + C)\tilde{w}(x_0, x_1) + (B + C)\tilde{w}(x_1, x_2). \end{aligned}$$

Then, we have $[I - (B + C)]\tilde{w}(x_1, x_2) \leq (A + B + C)\tilde{w}(x_0, x_1)$.

We get the inequality

$$\tilde{w}(x_1, x_2) \leq [I - (B + C)]^{-1}(A + B + C)\tilde{w}(x_0, x_1) = M\tilde{w}(x_0, x_1). \tag{3}$$

For the next step, we have

$$\begin{aligned} \tilde{w}(x_2, x_3) &= \tilde{w}(f(x_1), f(x_2))A\tilde{w}(x_1, x_2) + B[\tilde{w}(x_1, f(x_1)) + \tilde{w}(x_2, f(x_2))] + C[\tilde{w}(x_1, f(x_2)) \\ &+ \tilde{w}(x_2, f(x_1))] = A\tilde{w}(x_1, x_2) + B[\tilde{w}(x_1, x_2) + \tilde{w}(x_2, x_3)] + C[\tilde{w}(x_1, x_3) + \tilde{w}(x_2, x_2)] \\ &= (A + B)\tilde{w}(x_1, x_2) + B(\tilde{w}(x_2, x_3)) + C[\tilde{w}(x_1, x_2) + \tilde{w}(x_2, x_3)] \\ &= (A + B + C)\tilde{w}(x_1, x_2) + (B + C)\tilde{w}(x_2, x_3). \end{aligned}$$

Then, we have $[I - (B + C)]\tilde{w}(x_2, x_3) \leq (A + B + C)\tilde{w}(x_1, x_2)$.

Using (3) we obtain the inequality

$$\tilde{w}(x_2, x_3) \leq [I - (B + C)]^{-1}(A + B + C)\tilde{w}(x_1, x_2) = M\tilde{w}(x_1, x_2) \leq M^2\tilde{w}(x_0, x_1). \tag{4}$$

By induction we obtain a sequence $(x_n)_{n \in \mathbb{N}} \in X$, with $x_n = f(x_{n-1})$ such that

$$\tilde{w}(x_n, x_{n+1}) \leq M^n \tilde{w}(x_0, x_1), \tag{5}$$

with $M \in \mathcal{M}_{m,m}(\mathbb{R}_+)$ and $n \in \mathbb{N}$.

We will prove next that $(x_n)_{n \in \mathbb{N}}$ is a Cauchy sequence, by estimating $\tilde{w}(x_n, x_m)$, for every $m, n \in \mathbb{N}$ with $m > n$.

$$\begin{aligned} \tilde{w}(x_n, x_m) &\leq \tilde{w}(x_n, x_{n+1}) + \tilde{w}(x_{n+1}, x_{n+2}) + \dots + \tilde{w}(x_{m-1}, x_m) \\ &\leq M^n(\tilde{w}(x_0, x_1)) + M^{n+1}(\tilde{w}(x_0, x_1)) + \dots + M^{m-1}(\tilde{w}(x_0, x_1)) \\ &\leq M^n(I + M + M^2 + \dots + M^{m-n-1})(\tilde{w}(x_0, x_1)) \leq M^n(I - M)^{-1}\tilde{w}(x_0, x_1). \end{aligned}$$

Note that $(I - M)$ is nonsingular since M is convergent to zero. This implies

$$\lim_{n \rightarrow \infty} \tilde{w}(x_n, x_m) \leq \lim_{n \rightarrow \infty} M^n(I - M)^{-1}\tilde{w}(x_0, x_1) \xrightarrow{d} 0_{1 \times m}.$$

By Lemma 1 (3) the sequence $(x_n)_{n \in \mathbb{N}}$ is a Cauchy sequence.

By (a) we have $\tilde{w}(f(x_{n-1}), f(x^*)) \xrightarrow{d} 0_{1 \times m}$, as $n \rightarrow \infty$. As (X, d) is complete, there exists $x^* \in X$ such that $\lim_{n \rightarrow \infty} x_n \xrightarrow{d} x^*$ as $n \rightarrow \infty$. From the continuity of f , it follows that $x_{n+1} = f(x_n) \xrightarrow{d} f(x^*)$ as $n \rightarrow \infty$. By the uniqueness of the limit, we get $x^* = f(x^*)$, that is, x^* is a fixed point of f . Then $Fix(f) \neq \emptyset$.

Let $x^* \in X$ such that $x^* = f(x^*)$. Then, we have

$$\begin{aligned} \tilde{w}(x^*, x^*) &= \tilde{w}(f(x^*), f(x^*)) \leq A\tilde{w}(x^*, x^*) \\ &+ B[\tilde{w}(x^*, f(x^*)) + \tilde{w}(x^*, f(x^*))] + C[\tilde{d}(x^*, f(x^*)) + \tilde{d}(x^*, f(x^*))] \\ &= A\tilde{w}(x^*, x^*) + 2B\tilde{w}(x^*, x^*) + 2C\tilde{w}(x^*, x^*). \end{aligned} \tag{6}$$

This implies $[I - (A + 2B + 2C)]\tilde{w}(x^*, x^*) \leq 0_{1 \times m}$. By hypothesis (iii) we get $\tilde{w}(x^*, x^*) = 0_{1 \times m}$. \square

We can replace the continuity condition on the operator f and we obtain the following fixed point theorem.

Theorem 3. Let (X, \tilde{d}) be a complete generalized metric space in Perov's sense and $\tilde{w} : X \times X \rightarrow \mathbb{R}_+^m$ be a generalized w_0 -distance. Let $f : X \rightarrow X$ be a single-valued weakly Hardy–Rogers type operator such that the following conditions are satisfied,

- (a) $\inf\{\tilde{w}(x, y) + \tilde{w}(x, f(x)) : x \in X\} > 0$;
 (b) there exist matrices $A, B, C \in \mathcal{M}_{m,m}(\mathbb{R}_+)$ such that:
- (i) $M = (I - (B + C))^{-1}(A + B + C)$ converges to Θ ;
 - (ii) $I - (B + C)$ is nonsingular and $(I - (B + C))^{-1} \in \mathcal{M}_{m,m}(\mathbb{R}_+)$;
 - (iii) $I - (A + 2B + 2C)$ is nonsingular and $[I - (A + 2B + 2C)]^{-1} \in \mathcal{M}_{m,m}(\mathbb{R}_+)$.

Then $\text{Fix}(f) \neq \emptyset$. Moreover, if $x^* = f(x^*)$, then $w(x^*, x^*) = 0$.

Proof. Following the same steps as in the previous theorem, Theorem 2, we have the estimation

$$\tilde{w}(x_n, x_m) \leq M^n (I - M)^{-1} \tilde{w}(x_0, x_1) \quad (7)$$

with $M \in \mathcal{M}_{m,m}(\mathbb{R}_+)$ and $n \in \mathbb{N}$.

By Lemma 1 (3), the sequence $(x_n)_{n \in \mathbb{N}}$ is a Cauchy sequence. As (X, \tilde{d}) is complete, there exists $x^* \in X$ such that $x_n \xrightarrow{d} x^*$. Let $n \in \mathbb{N}$ be fixed. Then, as $(x_m)_{m \in \mathbb{N}} \xrightarrow{d} x^*$ and $\tilde{w}(x_n, \cdot)$ is lower semicontinuous, we have

$$\tilde{w}(x_n, x^*) \leq \liminf_{m \rightarrow \infty} \tilde{w}(x_n, x_m) \leq M^n (I - M)^{-1} \tilde{w}(x_0, x_1). \quad (8)$$

Assume that $x^* \neq f(x^*)$. Then, for every $x \in X$, by hypothesis (a) we have

$$\begin{aligned} 0 < \inf\{\tilde{w}(x, x^*) + \tilde{w}(x, f(x)) : x \in X\} &\leq \inf\{\tilde{w}(x_n, x^*) + \tilde{w}(x_n, x_{n+1}) : n \in \mathbb{N}\} \\ &\leq \inf\{M^n (I - M)^{-1} \tilde{w}(x_0, x_1) + M^n \tilde{w}(x_0, x_1)\} = 0. \end{aligned}$$

This is a contradiction. Therefore $x^* = f(x^*)$, so $\text{Fix}(f) \neq \emptyset$. For the proof of the last part of this theorem we use the same steps as is the previous theorem, Theorem 2. \square

Further we give a more general fixed point result concerning this new type of operators.

Theorem 4. Let (X, \tilde{d}) be a complete generalized metric space in Perov's sense, $\tilde{w} : X \times X \rightarrow \mathbb{R}_+^m$ be a generalized w_0 -distance, and $f : X \rightarrow X$ be a single-valued weakly Hardy–Rogers type operator. There exist matrices $A, B, C \in \mathcal{M}_{m,m}(\mathbb{R}_+)$ such that

- (i) $M = (I - (B + C))^{-1}(A + B + C)$ converges to Θ ;
- (ii) $I - (B + C)$ is nonsingular and $(I - (B + C))^{-1} \in \mathcal{M}_{m,m}(\mathbb{R}_+)$;
- (iii) $I - (A + 2B + 2C)$ is nonsingular and $[I - (A + 2B + 2C)]^{-1} \in \mathcal{M}_{m,m}(\mathbb{R}_+)$.

Then $\text{Fix}(f) \neq \emptyset$. Moreover, if $x^* = f(x^*)$, then $w(x^*, x^*) = 0$.

Proof. Following the same steps as in Theorem 2, we get the estimation

$$\tilde{w}(x_n, x_m) \leq M^n (I - M)^{-1} \tilde{w}(x_0, x_1) \quad (9)$$

with $M \in \mathcal{M}_{m,m}(\mathbb{R}_+)$ and $n \in \mathbb{N}$.

By Lemma 1 (3) the sequence $(x_n)_{n \in \mathbb{N}}$ is a Cauchy sequence; since (X, \tilde{d}) is complete there exists $x^* \in X$ such that $x_n \xrightarrow{d} x^*$.

Let $n \in \mathbb{N}$ be fixed. Then, as $(x_m)_{m \in \mathbb{N}} \xrightarrow{d} x^*$, $\tilde{w}(x_n, \cdot)$ is lower semicontinuous and letting $n \rightarrow \infty$ we have

$$\tilde{w}(x_n, x^*) \leq \liminf_{m \rightarrow \infty} \tilde{w}(x_n, x_m) \leq M^n (I - M)^{-1} \tilde{w}(x_0, x_1) \xrightarrow{d} 0_{1 \times m}. \quad (10)$$

Let $f(x^*) \in X$. By triangle inequality and using (6) we obtain

$$\begin{aligned}\tilde{w}(x_n, f(x^*)) &= \tilde{w}(x_n, x^*) + \tilde{w}(x^*, f(x^*)) \leq \tilde{w}(x_n, x^*) + \tilde{w}(f(x^*), f(x^*)) \\ &\leq M^n(I - M)^{-1}\tilde{w}(x_0, x_1) + [I - (A + 2B + 2C)]\tilde{w}(x^*, x^*) \xrightarrow{d} 0_{1 \times m}.\end{aligned}\quad (11)$$

Using Lemma 1(1), by Equations (10) and (11), we get $x^* = f(x^*)$. Then, $\text{Fix}(f) \neq \emptyset$.

For the last part of the proof we use the same steps as in Theorem 2. \square

Another fixed point result concerning the single-valued weakly Hardy–Rogers operators in generalized metric space is the following.

Theorem 5. Let (X, \tilde{d}) be a complete generalized metric space in Perov' sense, $\tilde{w} : X \times X \rightarrow \mathbb{R}_+^m$ be a generalized w_0 -distance and $f : X \rightarrow X$ be a single-valued Hardy–Rogers type operator. Suppose that all the hypothesis of Theorem 2 hold. Then, we have

- (1) $\text{Fix}(f) \neq \emptyset$.
- (2) There exists a sequence $(x_n)_{n \in \mathbb{N}} \in X$ such that $x_{n+1} = f(x_n)$, for all $n \in \mathbb{N}$ and converge to a fixed point of f .
- (3) $\tilde{d}(x_n, x^*) \leq M^n \tilde{d}(x_0, x_1)$, where $x^* \in \text{Fix}(f)$.

Example 1. Let $X = \mathbb{R}^2$ be a normed linear space endowed with the generalized norm \tilde{d} defined by $\tilde{d}(x, y) = \begin{pmatrix} \|x_1 - y_1\| \\ \|x_2 - y_2\| \end{pmatrix}$ and \tilde{w} a generalized w_0 -distance defined by $\tilde{w}(x, y) = \begin{pmatrix} \|y_1\| \\ \|y_2\| \end{pmatrix}$, for each $x = (x_1, x_2), y = (y_1, y_2) \in \mathbb{R}^2$. Let $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be an operator given by

$$f(x, y) = \begin{cases} \frac{4x}{5} + \frac{6y}{5} - 1, \frac{6y}{5} - 1, & \text{for } (x, y) \in \mathbb{R}^2, \text{ with } x \leq 5; \\ \frac{x}{5} + \frac{y}{3} - 1, \frac{y}{5}, & \text{for } (x, y) \in \mathbb{R}^2, \text{ with } x > 5. \end{cases}$$

We take $f(x, y) = (f_1(x, y), f_2(x, y))$ where $f_1(x, y) = \begin{cases} \frac{4x}{5} + \frac{6y}{5} - 1, & \text{for } (x, y) \in \mathbb{R}^2, \text{ with } x \leq 5; \\ \frac{x}{5} + \frac{y}{3} - 1, & \text{for } (x, y) \in \mathbb{R}^2, \text{ with } x > 5. \end{cases}$

and $f_2(x, y) = \begin{cases} \frac{6y}{5} - 1, & \text{for } (x, y) \in \mathbb{R}^2, \text{ with } x \leq 5; \\ \frac{y}{5}, & \text{for } (x, y) \in \mathbb{R}^2, \text{ with } x > 5. \end{cases}$

Next, we show that weakly Hardy–Rogers type condition takes place.

$$\text{Let } A = \begin{pmatrix} \frac{4}{5} & \frac{6}{5} \\ 0 & \frac{6}{5} \end{pmatrix}.$$

Case 1. If $1 \leq x_1, x_2, y_1, y_2 \leq 5$ we have

$$\begin{aligned}\tilde{w}(f(x), f(y)) &= \begin{pmatrix} \|f_1(y_1, y_2)\| \\ \|f_2(y_1, y_2)\| \end{pmatrix} = \begin{pmatrix} \|\frac{4}{5}y_1 + \frac{6}{5}y_2 - 1\| \\ \|0 \cdot y_1 + \frac{6}{5}y_2 - 1\| \end{pmatrix} \leq \begin{pmatrix} \frac{4}{5}\|y_1\| + \frac{6}{5}\|y_2\| - 1 \\ 0 \cdot \|y_1\| + \frac{6}{5}\|y_2\| - 1 \end{pmatrix} \\ &\leq \begin{pmatrix} \frac{4}{5} & \frac{6}{5} \\ 0 & \frac{6}{5} \end{pmatrix} \begin{pmatrix} \|y_1\| \\ \|y_2\| \end{pmatrix} = A\tilde{w}(x, y).\end{aligned}$$

Case 2. If $x_1, x_2, y_1, y_2 > 5$ we have

$$\begin{aligned}\tilde{w}(f(x), f(y)) &= \begin{pmatrix} \|f_1(y_1, y_2)\| \\ \|f_2(y_1, y_2)\| \end{pmatrix} = \begin{pmatrix} \|\frac{1}{5}y_1 + \frac{1}{3}y_2 - 1\| \\ \|0 \cdot y_1 + \frac{1}{5}y_2\| \end{pmatrix} \leq \begin{pmatrix} \frac{1}{5}\|y_1\| + \frac{1}{3}\|y_2\| - 1 \\ 0 \cdot \|y_1\| + \frac{1}{5}\|y_2\| \end{pmatrix} \\ &\leq \begin{pmatrix} \frac{1}{5} & \frac{1}{3} \\ 0 & \frac{1}{5} \end{pmatrix} \begin{pmatrix} \|y_1\| \\ \|y_2\| \end{pmatrix} < \begin{pmatrix} \frac{4}{5} & \frac{6}{5} \\ 0 & \frac{6}{5} \end{pmatrix} \begin{pmatrix} \|y_1\| \\ \|y_2\| \end{pmatrix} = A\tilde{w}(x, y).\end{aligned}$$

Case 3. For other choices of x_1, x_2, y_1, y_2 we have

$$\tilde{w}(f(x), f(y)) = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \leq \begin{pmatrix} \frac{4}{5} & \frac{6}{5} \\ 0 & \frac{6}{5} \end{pmatrix} \begin{pmatrix} \|y_1\| \\ \|y_2\| \end{pmatrix} = A\tilde{w}(x, y).$$

Thus, the weakly Hardy–Rogers type condition is satisfied for $A = \begin{pmatrix} \frac{4}{5} & \frac{6}{5} \\ 0 & \frac{6}{5} \end{pmatrix}$ and $B = C = \Theta$ or $B + C = \Theta$.

As all the hypothesis of Theorem 3 hold, f has a fixed point and it is easy to check that $x = f(x) = (f_1(x), f_2(x))$, where $x = (1, 1)$.

Next, let us give some common fixed point results.

Theorem 6. Let (X, \tilde{d}) be a complete generalized metric space in Perov’s sense, $\tilde{w} : X \times X \rightarrow \mathbb{R}_+^m$ be a generalized w -distance, and $f, g : X \rightarrow X$ be two continuous single-valued weakly Hardy–Rogers type operators. There exist matrices $A, B, C \in \mathcal{M}_{m,m}(\mathbb{R}_+)$ such that

- (i) $I - (B + C)$ is nonsingular and $(I - (B + C))^{-1} \in \mathcal{M}_{m,m}(\mathbb{R}_+)$;
- (ii) $M = (I - (B + C))^{-1}(A + B + C)$ converges to Θ .

Then, f and g have a common fixed point $x^* \in X$.

Proof. (1) Let $x_0 \in X$. We consider $(x_n)_{n \in \mathbb{N}}$ the sequence of successive approximations for f and g , defined by

$$\begin{aligned} x_{2n+1} &= f(x_{2n}), n = 0, 1, \dots \\ x_{2n+2} &= g(x_{2n+1}), n = 0, 1, \dots \end{aligned}$$

Then, we have

$$\begin{aligned} \tilde{w}(x_{2n}, x_{2n+1}) &= \tilde{w}(g(x_{2n-1}), f(x_{2n})) \leq A\tilde{w}(x_{2n-1}, f(x_{2n})) \\ &+ B[\tilde{w}(x_{2n}, f(x_{2n})) + \tilde{w}(x_{2n-1}, g(x_{2n-1}))] + C[\tilde{w}(x_{2n}, g(x_{2n-1})) + \tilde{w}(x_{2n-1}, f(x_{2n}))] \\ &= A\tilde{w}(x_{2n-1}, x_{2n}) + B[\tilde{w}(x_{2n}, x_{2n+1}) + \tilde{w}(x_{2n-1}, x_{2n})] + C\tilde{w}(x_{2n-1}, x_{2n+1}) \\ &\leq A\tilde{w}(x_{2n-1}, x_{2n}) + B[\tilde{w}(x_{2n}, x_{2n+1}) + \tilde{w}(x_{2n-1}, x_{2n})] + C[\tilde{w}(x_{2n-1}, x_{2n}) + \tilde{w}(x_{2n}, x_{2n+1})]. \end{aligned}$$

Then, we have $\tilde{w}(x_{2n}, x_{2n+1}) \leq (I - (B + C))^{-1}(A + B + C)\tilde{w}(x_{2n-1}, x_{2n}) = M\tilde{w}(x_{2n-1}, x_{2n})$.
By the same argument as above, we get

$$\begin{aligned} \tilde{w}(x_{2n+1}, x_{2n+2}) &= \tilde{w}(f(x_{2n}), g(x_{2n+1})) \leq A\tilde{d}(x_{2n}, f(x_{2n+1})) \\ &+ B[\tilde{w}(x_{2n}, f(x_{2n})) + \tilde{w}(x_{2n+1}, g(x_{2n+1}))] + C[\tilde{w}(x_{2n}, g(x_{2n+1})) + \tilde{w}(x_{2n+1}, f(x_{2n}))] \\ &= A\tilde{w}(x_{2n}, x_{2n+1}) + B[\tilde{w}(x_{2n}, x_{2n+1}) + \tilde{w}(x_{2n+1}, x_{2n+2})] + C\tilde{w}(x_{2n}, x_{2n+2}) \\ &\leq A\tilde{w}(x_{2n}, x_{2n+1}) + B[\tilde{w}(x_{2n}, x_{2n+1}) + \tilde{w}(x_{2n+1}, x_{2n+2})] + C[\tilde{w}(x_{2n}, x_{2n+1}) + \tilde{w}(x_{2n+1}, x_{2n+2})]. \end{aligned}$$

Then, we have $\tilde{w}(x_{2n+1}, x_{2n+2}) \leq (I - (B + C))^{-1}(A + B + C)\tilde{w}(x_{2n}, x_{2n+1}) = M\tilde{w}(x_{2n}, x_{2n+1})$.

Further, we obtain $\tilde{w}(x_n, x_{n+1}) \leq M^n \tilde{w}(x_0, x_1)$ for each $n \in \mathbb{N}$.

Following the same steps as in the proof of Theorem 2 we estimate $\tilde{w}(x_n, x_m)$, for every $m, n \in \mathbb{N}$ with $m > n$.

$$\begin{aligned} \tilde{w}(x_n, x_m) &\leq \tilde{w}(x_n, x_{n+1}) + \tilde{w}(x_{n+1}, x_{n+2}) + \dots + \tilde{w}(x_{m-1}, x_m) \\ &\leq M^n(\tilde{w}(x_0, x_1)) + M^{n+1}(\tilde{w}(x_0, x_1)) + \dots + M^{m-1}(\tilde{w}(x_0, x_1)) \\ &\leq M^n(I + M + M^2 + \dots + M^{m-n-1})(\tilde{w}(x_0, x_1)) \leq M^n(I - M)^{-1}\tilde{w}(x_0, x_1). \end{aligned}$$

Note that $(I - M)$ is nonsingular since M is convergent to Θ . Using Lemma 1 (3) the sequence $(x_n)_{n \in \mathbb{N}}$ is a Cauchy sequence.

Using the lower semicontinuity of the generalized w -distance, by relation (8) we have $\tilde{w}(x_n, x^*) \xrightarrow{d} 0_{1 \times m}$ as $n \rightarrow \infty$. Then, we have $\tilde{w}(x_{2n}, x^*) \xrightarrow{d} 0_{1 \times m}$ as $n \rightarrow \infty$. By the continuity of f it follows $x_{2n+1} = f(x_{2n}) \xrightarrow{d} f(x^*)$ as $n \rightarrow \infty$. By the uniqueness of the limit we get $x^* = f(x^*)$.

By $\tilde{w}(x_n, x^*) \xrightarrow{d} 0_{1 \times m}$ as $n \rightarrow \infty$ we have that $\tilde{w}(x_{2n+1}, x^*) \xrightarrow{d} 0_{1 \times m}$ as $n \rightarrow \infty$. By the continuity of g it follows $x_{2n+2} = g(x_{2n+1}) \xrightarrow{d} g(x^*)$ as $n \rightarrow \infty$. By the uniqueness of the limit we get $x^* = g(x^*)$. Then, x^* is a common fixed point for f and g . \square

By replacing the continuity condition for the mappings f and g , we can state the following result.

Theorem 7. Let (X, \tilde{d}) be a complete generalized metric space in Perov's sense, $\tilde{w} : X \times X \rightarrow \mathbb{R}_+^m$ be a generalized w -distance, and $f, g : X \rightarrow X$ be two single-valued Hardy–Rogers type operators. There exist matrices $A, B, C \in \mathcal{M}_{m,m}(\mathbb{R}_+)$ such that

- (i) $I - (B + C)$ is nonsingular and $(I - (B + C))^{-1} \in \mathcal{M}_{m,m}(\mathbb{R}_+)$;
- (ii) $I - (A + 2B + 2C)$ is nonsingular and $[I - (A + 2B + 2C)]^{-1} \in \mathcal{M}_{m,m}(\mathbb{R}_+)$;
- (iii) $M = (I - (B + C))^{-1}(A + B + C)$ converges to Θ .

Then f and g have a common fixed point $x^* \in X$.

Proof. (1) As in the proof of the previous theorem, Theorem 6, for $x_0 \in X$ we consider $(x_n)_{n \in \mathbb{N}}$ the sequence of successive approximations for f and g , defined by

$$x_{2n+1} = f(x_{2n}), n = 0, 1, \dots$$

$$x_{2n+2} = g(x_{2n+1}), n = 0, 1, \dots$$

We define the sequence $(x_n)_{n \in \mathbb{N}} \in X$ such that

$$\tilde{w}(x_{2n+1}, x_{2n+2}) \leq (I - (B + C))^{-1}(A + B + C)\tilde{w}(x_{2n}, x_{2n+1}) = M\tilde{w}(x_{2n}, x_{2n+1}).$$

Further, we obtain $\tilde{w}(x_n, x_{n+1}) \leq M^n \tilde{d}(x_0, x_1)$ for each $n \in \mathbb{N}$.

Following the same steps as in the proof of Theorem 6 we estimate $\tilde{w}(x_n, x_m)$, for every $m, n \in \mathbb{N}$ with $m > n$ and we get $\tilde{w}(x_n, x_m) \leq M^n (I - M)^{-1} \tilde{w}(x_0, x_1)$.

Note that $(I - M)$ is nonsingular since M is convergent to Θ . By Lemma 1 (3), the sequence $(x_n)_{n \in \mathbb{N}}$ is a Cauchy sequence. Using the lower semicontinuity of the generalized w -distance, by relation (8), we have $\tilde{w}(x_n, x^*) \xrightarrow{d} 0_{1 \times m}$, as $n \rightarrow \infty$. By (11) we have $\tilde{w}(x_n, f(x^*)) \xrightarrow{d} 0_{1 \times m}$, as $n \rightarrow \infty$. Then, using Lemma 1 (2), we get $x^* = f(x^*)$.

Let us show that $g(x^*) = x^*$. Then, by the definition of Hardy–Rogers type operators we have

$$\tilde{w}(x^*, g(x^*)) = \tilde{d}(f(x^*), g(x^*))$$

$$\leq A\tilde{w}(x^*, x^*) + B[\tilde{w}(x^*, f(x^*)) + \tilde{w}(x^*, g(x^*))] + C[\tilde{w}(x^*, g(x^*)) + \tilde{w}(x^*, f(x^*))].$$

Then, we get

$$\tilde{w}(x^*, g(x^*)) \leq (I - (B + C))^{-1}(A + B + C)\tilde{w}(x^*, x^*). \quad (12)$$

By (6) we get $\tilde{w}(x^*, g(x^*)) = 0_{1 \times m}$.

Let $g(x^*) \in X$. By triangle inequality and using (12) we obtain

$$\tilde{w}(x_n, g(x^*)) = \tilde{w}(x_n, x^*) + \tilde{w}(x^*, g(x^*)) \leq M^n (I - M)^{-1} \tilde{w}(x_0, x_1) + 0_{1 \times m} \xrightarrow{d} 0_{1 \times m}. \quad (13)$$

Using (8) and (13), by Lemma 1 (2), we obtain $x^* = g(x^*)$. Then x^* is a common fixed point for f and g . \square

Remark 3. In the case of common fixed points, the generalized \tilde{w} -distance must not necessarily be a generalized \tilde{w}_0 -distance.

3. Ulam–Hyers Stability, Well-Posedness, and Data Dependence of Fixed Point Problem

We begin this section with the extension of Ulam–Hyers stability for fixed point equation for the case of single-valued operators on generalized metric space in Perov’s sense. Then, let us recall the definition of weakly Ulam–Hyers stability.

Definition 9. Let (X, \tilde{d}) be a metric space, $\tilde{w} : X \times X \rightarrow \mathbb{R}_+^m$ be a generalized w -distance, and $f : X \rightarrow X$ be an operator. By definition, the fixed point equation

$$x = f(x) \tag{14}$$

is weakly Ulam–Hyers stable if there exists a real positive matrix $N \in \mathcal{M}_{m,m}(\mathbb{R}_+)$ such that, for each $\varepsilon > 0$ and each solution y^* of the inequation

$$\tilde{w}(y, f(y)) \leq \varepsilon I_{1 \times m} \tag{15}$$

there exists a solution x^* of the Equation (14) such that

$$\tilde{d}(y^*, x^*) \leq N\varepsilon I_{1 \times m}.$$

Theorem 8. Let (X, \tilde{d}) be a generalized metric space in Perov’s sense, $\tilde{w} : X \times X \rightarrow \mathbb{R}_+^m$ be a generalized w_0 -distance and $f : X \rightarrow X$ be a single-valued Hardy–Rogers type operator defined in (8). There exist matrices $A, B, C \in \mathcal{M}_{m,m}(\mathbb{R}_+)$ such that

- (i) $N = M^n(I - M)^{-1}$ is nonsingular and $N = M^n(I - M)^{-1} \in \mathcal{M}_{m,m}(\mathbb{R}_+)$, where $M = (I(B + C))^{-1}(A + B + C)$ converges to Θ ;
- (ii) $I - (A + 2B + 2C)$ is nonsingular and $[I - (A + 2B + 2C)]^{-1} \in \mathcal{M}_{m,m}(\mathbb{R}_+)$;
- (iii) $I - P^2$ is nonsingular and $I - P^2 \in \mathcal{M}_{m,m}(\mathbb{R}_+)$ where $P = [I - (A + C)]^{-1}C \in \mathcal{M}_{m,m}(\mathbb{R}_+)$.

Then, the fixed point Equation (14) is weakly Ulam–Hyers stable.

Proof. Let $\delta I_{1 \times m} > 0_{1 \times m}$ such that $\tilde{w}(x_0, x_1) \leq \delta I_{1 \times m}$, for every $x_0, x_1 \in X$ with $x_1 = f(x_0)$. Let $Fix(f) = \{x^*\}$ and $u^* \in X$ be a solution of Equation (14). Then, $\tilde{w}(u^*, f(u^*)) \leq \varepsilon I_{1 \times m}$. By the definition of the weakly Hardy–Rogers type operator we obtain

$$\begin{aligned} \tilde{w}(x^*, u^*) &\leq \tilde{w}(f(x^*), f(u^*)) \leq A\tilde{w}(x^*, u^*) + B[\tilde{w}(x^*, f(x^*)) + \tilde{w}(u^*, f(u^*))] + C[\tilde{w}(x^*, f(u^*)) \\ &+ \tilde{w}(u^*, f(x^*))] = A\tilde{w}(x^*, u^*) + B[\tilde{w}(x^*, x^*) + \tilde{w}(u^*, u^*)] + C[\tilde{w}(x^*, u^*) + \tilde{w}(u^*, x^*)] \tag{16} \\ &= (A + C)\tilde{w}(x^*, u^*) + B[\tilde{w}(x^*, x^*) + \tilde{w}(u^*, u^*)] + C\tilde{w}(u^*, x^*). \end{aligned}$$

By (6) we get

$$\tilde{w}(x^*, x^*) = \tilde{w}(f(x^*), f(x^*)) \leq (A + 2B + 2C)\tilde{w}(x^*, x^*) \text{ and} \tag{17}$$

$$\tilde{w}(u^*, u^*) = \tilde{w}(f(u^*), f(u^*)) \leq (A + 2B + 2C)\tilde{w}(u^*, u^*).$$

Using hypothesis (ii) we get $\tilde{w}(x^*, x^*) = \tilde{w}(u^*, u^*) = 0_{1 \times m}$.

By (16) we obtain

$$\tilde{w}(x^*, u^*) \leq [I - (A + C)]^{-1}C\tilde{w}(u^*, x^*). \tag{18}$$

By the definition of the weakly Hardy–Rogers type operator we get

$$\tilde{w}(u^*, x^*) \leq [I - (A + C)]^{-1}C\tilde{w}(x^*, u^*)$$

and using (18) we obtain

$$\tilde{w}(x^*, u^*) \leq ([I - (A + C)]^{-1}C)^2\tilde{w}(x^*, u^*) = P^2\tilde{w}(x^*, u^*). \tag{19}$$

Then, $(I - P^2)\tilde{w}(x^*, u^*) \leq 0_{1 \times m}$. By hypothesis (iii) we get $\tilde{w}(x^*, u^*) = 0_{1 \times m}$. Let $x_n \in X$ such that, by Equations (8) and (19) we have

$$\tilde{w}(x_n, x^*) \leq M^n(I - M)^{-1}\tilde{w}(x_0, x_1) \leq N\delta I_{1 \times m} \text{ and} \tag{20}$$

$$\tilde{w}(x_n, u^*) \leq \tilde{w}(x_n, x^*) + \tilde{w}(x^*, u^*) \leq M^n(I - M)^{-1}\tilde{w}(x_0, x_1) + 0_{1 \times m} \leq N\delta I_{1 \times m}.$$

Then, using the definition of generalized w -distance, there exists $\varepsilon I_{1 \times m} > 0_{1 \times m}$ such that

$$\tilde{d}(x^*, u^*) \leq \varepsilon I_{1 \times m} \leq N\varepsilon I_{1 \times m}.$$

Then, the fixed point Equation (14) is weakly Ulam–Hyers stable.

□

The following result assures the well-posedness of the fixed point problem with respect to the generalized w_0 -distance \tilde{w} .

Theorem 9. Let (X, \tilde{d}) be a generalized metric space in Perov’s sense, $\tilde{w} : X \times X \rightarrow \mathbb{R}_+^m$ be a generalized w_0 -distance, and $f : X \rightarrow X$ be a single-valued Hardy–Rogers type operator defined in Equation (8). If all the hypothesis of Theorem 2 (respectively, 3 and 4) are satisfied, the fixed point Equation (14) is well-posed with respect to the generalized w_0 -distance \tilde{w} , i.e., if $\text{Fix}(f) = \{x^*\}$ and $x_n \in \mathbb{N}$, with $n \in \mathbb{N}$, such that $\tilde{w}(x_n, f(x_n)) \rightarrow 0_{1 \times m}$ as $n \rightarrow \infty$, then $x_n \rightarrow x^*$ as $n \rightarrow \infty$.

Proof. Let $x^* \in \text{Fix}(f)$ and let $(x)_{n \in \mathbb{N}} \in X$ such that $\tilde{w}(x_n, f(x_n)) \xrightarrow{d} 0_{1 \times m}$ as $n \rightarrow \infty$. That means $\tilde{w}(x_{n-1}, x_n) \xrightarrow{d} 0_{1 \times m}$ as $n \rightarrow \infty$.

By the lower semicontinuity of the generalized w -distance, using (8) we have

$$\tilde{w}(x_{n-1}, x^*) \leq \liminf_{m \rightarrow \infty} \tilde{w}(x_n, x_m) \leq M^n(I - M)^{-1}\tilde{w}(x_0, x_1) \xrightarrow{d} 0_{1 \times m}.$$

Then, using Lemma 1 (3) we get $x_n \xrightarrow{d} x^*$ as $n \rightarrow \infty$. □

The next theorem presents a data dependence result.

Theorem 10. Let (X, \tilde{d}) be a generalized metric space in Perov’s sense, $\tilde{w} : X \times X \rightarrow \mathbb{R}_+^m$ be a generalized w_0 -distance, and $f_1, f_2 : X \rightarrow X$ be single-valued operators, which satisfy the following conditions,

- (i) for $A, B, C, M \in \mathcal{M}_{m,m}(\mathbb{R}_+)$ with $M = [I - (B + C)]^{-1}(A + B + C)$ a matrix convergent to Θ such that, for every $x, y \in X$ and $i \in \{1, 2\}$, we have:

$$\tilde{w}(f_i(x), f_i(y)) \leq A\tilde{w}(x, y) + B[\tilde{w}(x, f_i(x)) + \tilde{w}(y, f_i(y))] + C[\tilde{w}(x, f_i(y)) + \tilde{w}(y, f_i(x))];$$
- (ii) there exists $\eta > 0$ such that $\tilde{w}(f_1(x), f_2(x)) \leq \eta I$, for all $x \in X$.

Then, for $x_1^* = f_1(x_1^*)$ there exists $x_2^* = f_2(x_2^*)$ such that $\tilde{d}(x_1^*, x_2^*) \leq (I - M)^{-1}\eta I_{1 \times m}$; (respectively, for $x_2^* = f_2(x_2^*)$ there exists $x_1^* = f_1(x_1^*)$ such that $\tilde{w}(x_2^*, x_1^*) \leq (I - M)^{-1}\eta I_{1 \times m}$).

Proof. As in the proof of Theorem 2 (respectively, Theorem 3) we construct the sequence of successive approximations $(x_n)_{n \in \mathbb{N}} \in X$ of f_2 with $x_0 := x_1^*$ and $x_1 = f_2(x_1^*)$ having the property $\tilde{w}(x_n, x_{n+1}) \leq M^n \tilde{w}(x_0, x_1)$, where $M = [I - (B + C)]^{-1}(A + B + C)$.

If we consider the sequence $(x_n)_{n \in \mathbb{N}} \in X$ converges to x_2^* , we have $x_2^* = f(x_2^*)$. Moreover, for each $n, p \in \mathbb{N}$ we have $\tilde{w}(x_n, x_{n+p}) \leq M^n (I - M)^{-1} \tilde{w}(x_0, x_1)$.

Letting $p \rightarrow 0$ we get $\tilde{w}(x_n, x_2^*) \leq I(I - M)^{-1} \tilde{w}(x_0, x_1)$.

Choosing $n = 0$ we get $\tilde{w}(x_0, x_2^*) \leq I(I - M)^{-1} \tilde{w}(x_0, x_1)$ and using above the notations we get our conclusion $\tilde{w}(x_1^*, x_2^*) \leq (I - M)^{-1} \eta I_{1 \times m}$. \square

4. Conclusions

The purpose of this paper is to establish some fixed point results in generalized metric spaces in Perov's sense. The generalized metric considered here is the w -distance, for which the symmetry condition is not satisfied. The operators satisfy a contractive weakly condition of Hardy–Rogers type. The second part of the paper is devoted to the study of the data dependence, as well as the well-posedness and the Ulam–Hyers stability of the fixed point problem. In order to prove our main results we had to impose a symmetry condition for the w -distance. The results presented in this paper generalize some recent ones.

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