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Section Networks

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Section Information

The Network Section provides full coverage of all topics of interest involved in the networking area. The purpose of this Section is to bring together researchers, engineers, and students from academia and industry to present novel ideas and solid research about the theoretical and practical aspects in the application domains of computer communications and networks.

The primary focus of the section is on the analysis, modeling, design, simulation, and implementation of computer networks, from wired systems to wireless systems. The section will also serve to attract research concerning applying networking architectures and scenarios to emerging research topics, such as IoT, smart cities, edge computing, ITS, and unmanned aerial vehicles, among others.

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Selected Papers



An Automotive Reference Testbed with Trusted Security Services

Authors: Teri Lenard, Béla Genge, Piroska Haller, Anastasija Collen and Niels Alexander Nijdam

Abstract: While research in the field of automotive systems inclined in the past years towards technologies such as Vehicle-to-Everything (V2X) or Connected and Automated Vehicle (CAV), the underlying system security still plays a crucial role in assuring trust and system safety. The work at hand tackles the issue of automotive system security by designing a multi-service security system specially tailored for in-vehicle networks. The proposed trusted security services leverage Trusted Platform Module (TPM) to store secrets and manage and exchange cryptographic keys. To showcase how security services can be implemented in a in-vehicle network, a Reference TestBed (RTB) was developed. In the RTB, encryption and authentication keys are periodically exchanged, data is sent authenticated, the network is monitored by a Stateful Firewall and Intrusion Detection System (SF/IDS), and security events are logged and reported. A formal individual and multi-protocol analysis was conducted to demonstrated the feasibility of the proposed services from a theoretical point of view. Two distinct scenarios were considered to present the workflow and interaction between the proposed services. Lastly, performance measurements on the reference hardware are provided.

<https://doi.org/10.3390/electronics12040888>



Random Routing Algorithm for Enhancing the Cybersecurity of LEO Satellite Networks

Authors: Ruben Fratty, Yuval Saar, Rajnish Kumar and Shlomi Arnon

Abstract: The recent expansion of networks of low-earth orbit (LEO) satellites such as Starlink, OneWeb, and Telesat and the evolution of communication systems toward B5G and 6G with densely interconnected devices could generate opportunities for various cyber attacks. As the satellite network offers many crucial services to the public and governmental organizations, cyberattacks pose severe risks to the communication infrastructure. In this study, we propose a random routing algorithm to prevent distributed denial-of-service (DDoS) attacks on an LEO satellite constellation network. The routing algorithm utilizes the classical algorithms, i.e., k-DG, k-DS, k-SP, and k-LO, by introducing randomness and selecting one with weighted probability distribution to increase the uncertainty in the algorithm. The study shows that the proposed random routing algorithm improves the average and median cost of the attacker against DDoS attacks while maintaining the functionality of the network. The algorithm is optimized by formulating a Bayesian optimization problem. In addition to providing an additional level of uncertainty in the routing, there is an improvement of 1.71% in the average cost and 2.05% in the median cost in a typical scenario. The algorithm causes the network to be robust to cyber attacks against LEO Satellite Networks (LSNs), however, similar to any other defensive measures, it reduces the network's goodput.

<https://doi.org/10.3390/electronics12030518>



DOA Estimation Based on Convolutional Autoencoder in the Presence of Array Imperfections

Authors: Dah-Chung Chang and Yan-Ting Liu

Abstract: Array imperfections may exist in an antenna system subject to non-ideal design and practical limitations. It is difficult to accurately model array imperfections, and thus complicated algorithms are usually inevitable for model-based methods to estimate the direction of arrival (DOA) with imperfect arrays. Deep neural network (DNN)-based methods do not need to rely on pre-modeled antenna array geometries, and have been explored to handle flawed array models because of their better flexibility than model-based methods. The DNN autoencoder (DAE) method has been proposed for the array imperfection problem, which decomposes the input into multiple components in different spatial subregions. These components have more concentrated distributions than the original input, which avoid a large number of connections and nodes used in the layers to realize DOA estimation classifiers. In this paper, we study the convolutional AE (CAE) method that substantially focuses on the learning of local features in a different manner from the previous DAE method. The advantage of the convolutional operation using a kernel in CAE is to capture features in a more efficient manner than the DAE, and thus be able to reduce the number of parameters that are required to be trained in the neural networks. From the numerical evaluation of DOA estimation accuracy, the proposed CAE method is also more resistant to the noise effect than the DAE method such that the CAE method has better accuracy at a lower signal-to-noise ratio.

<https://doi.org/10.3390/electronics12030771>



3D Hybrid Localization Algorithm for Mitigating NLOS Effects in Flying Ad Hoc Networks

Author: Jung Min Pak

Abstract: Positions of unmanned aerial vehicles (UAVs) are typically obtained using the global positioning system (GPS). However, in GPS-denied or GPS-degraded environments, ad hoc networks with flying sensor nodes are used for UAV localization. In this study, we propose a novel three-dimensional (3D) localization algorithm for UAVs in flying ad hoc sensor networks. Interacting multiple model probability data association and finite impulse response filters are integrated in our hybrid localization algorithm. The non-line-of-sight condition can be overcome using the proposed algorithm, which is demonstrated through 3D localization simulations based on flying ad hoc networks.

<https://doi.org/10.3390/electronics12030503>

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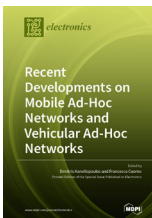


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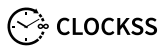
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