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Thermal Model Developments for Electrified Vehicles

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Abstract
Argonne National Laboratory has analyzed the control behavior of advanced vehicles, such as hybrid electric vehicles (HEVs), plug-in hybrid electric vehicles (PHEVs), and battery electric vehicles (BEVs), to develop simulation models and to reproduce the performance of vehicles with simulation techniques. Since many of the novel and advanced studies about transportation technologies done at Argonne use these simulation techniques, they must be well-validated to conduct and support these studies. To improve its research ability, Argonne built a new testing facility that can test vehicles under different thermal conditions (e.g., −7°C or 35°C), and it has analyzed the controls and performance of several advanced vehicles under these conditions. Further, Argonne has used the analyzed results to develop thermal component models that reproduce the thermal behavior of the vehicles. A main reason to develop thermal models is that the thermal conditions have such a significantly large impact on vehicle performance, especially with regard to advanced vehicles like HEVs or PHEVs. For instance, engine and battery efficiencies must decrease at low temperatures since the battery might not be able to provide enough power if it is very cold. Moreover, the climate control system still has a great demand for additional energy under very cold weather conditions even if the engine is not operating at all. The test data obtained from Argonne’s Advanced Powertrain Research Facility (APRF) are analyzed in order to understand the thermal impacts on controls and performance, and the thermal models are developed based on the analyzed results and validated with the test data. In comparative studies, the simulation models have been found to reproduce fuel consumption that is very close to the fuel consumption obtained from the tests.

Keywords: Hybrid Electric Vehicle, Thermal Model, Control, Dynamometer Test, Fuel Economy

1 Introduction
Electrified vehicles such as hybrid electric vehicles (HEVs), plug-in hybrid electric vehicles (PHEVs), and battery electric vehicles (BEVs) are able to save fossil fuels by optimizing the engine’s operations, recuperating the braking energy, or using electric energy instead of the fuel. Simply stated, the electrified vehicles have an additional degree of freedom to manage energy by being able to split the power between the fuel and electricity, whereas a conventional vehicle only uses the fuel. One issue that arises from this additional capability is that the engine might not provide enough waste heat to warm up a passenger compartment or the powertrain components, including the engine itself. [1] Because of that, the electrified vehicles may suffer from the inefficient operation of the
powertrain components under very cold ambient temperatures [2]-[3]. For instance, Figure 1 compares the energy consumption results for four types of electrified vehicles; they were obtained from chassis dynamometer tests done at different ambient room temperatures.

The results show that electrified vehicles consume a lot of fuel or electricity in cold ambient temperature tests (−7°C): almost twice as much as they use in normal ambient temperature tests (21°C). The increase in energy consumption is caused by the heat load demand from the passenger compartment or by the low efficiency of the engine’s operations; the increase is so significantly large that the new test procedures published by U.S. Environmental Protection Agency (EPA) include additional tests under cold and hot ambient conditions for the fuel economy labels of vehicles produced in 2008 or later. For the same reason, developing thermal models for the electrified vehicles is also very important; the fuel efficiencies of the vehicles should include the impact of thermal conditions. Argonne National Laboratory has been developing a number of advanced vehicle models, including electrified vehicles, to analyze the impacts of new technologies on fuel efficiency and market penetration [4]-[6]. Also, the laboratory has been conducting various studies to improve fuel efficiency by optimizing the control algorithm or the vehicle parameters. In recent years, Argonne has been adding value by improving the model’s fidelity, and one ongoing effort is to develop the vehicle’s thermal management system [1]. This brief provides information about the entire process — conducting the tests, analyzing the test data, and developing the vehicle model — so that the process can be used in other studies.

2 Control and Performance Analysis

To have well validated simulation models, it is also very important to have well qualified test results. Based on the test results, the performance of the vehicle components can be analyzed, and the control of the vehicle system can be also analyzed before being implemented into the simulation models.

2.1 Chassis Dynamometer Tests

Argonne built the Advanced Powertrain Research Facility (APRF), which has a chassis dynamometer in a thermal chamber, to be a testing facility that can evaluate the fuel consumption and emissions of advanced vehicles under different thermal conditions (Figure 2) [7], [8].

The facility is able to control room temperatures, so the vehicles can be tested to evaluate their performance under different ambient room temperatures like −7°C or 35°C. Additional instruments like solar lamps and fans are also implemented to mimic real world operating conditions. In the facility, Argonne has been testing many advanced vehicles, and the testing results are selectively available at the website [9], [10].

2.2 Performance Analysis

The main goal of the performance analysis for thermal model development is to determine the impact of temperature on a powertrain component’s efficiency. Figures 3 and 4 show two examples for the performance analysis: Figure 3 is for the engine, and Figure 4 is for the battery. The test results for Figure 3 show that the engine’s fuel consumption rate is changed mostly by the engine’s speed and the engine’s torque but is also significantly changed by the engine’s coolant temperature.
Figure 3. The engine fuel consumption rate according to the engine coolant temperature

On the other hand, Figure 4 results show that the internal resistance, which affects the battery efficiency, also significantly changes according to the battery temperature.

Figure 4. The internal resistance of the battery obtained from test data

Based on the analysis of the test data, the performance of the powertrain components can be applied in the simulation models.

### 2.3 Control Analysis

The other important step in the analysis process is to analyze the control behavior of the real world vehicle. The goal of the vehicle model development is to evaluate the vehicle’s performance in simulation environments, for which the control used in the real world vehicle should be well implemented in the control model. For instance, Figure 5 shows the engine on/off condition of a Toyota Prius HEV according to the vehicle speed and wheel torque demand, and Figure 6 shows that the on/off condition changes according to the thermal condition of the engine.

Figure 5. Engine on/off analysis based on test data

On the other hand, Figures 7 and 8 were obtained by analyzing the test data for the battery, which show that the output power of the battery is controlled by its State of Charge (SOC), and that battery power is limited according to the battery temperature.

Figure 6. The engine on/off condition as changed by the level of the engine coolant temperature

Figure 7. The battery’s desired power as determined by the SOC level
The control model for each vehicle is developed based on the analysis results, so that the vehicle model in the simulation can provide the same control behavior as the real world vehicle does.

3 Thermal Model Development

The thermal components in the powertrain components can be coupled to each other as shown in Figure 9, so it is not easy to develop generic configurations for the thermal management system.

3.1 Thermal Component Model
This brief introduces the fundamental ideas for developing the powertrain thermal component models here.

3.1.1 Engine Thermal Model
The engine thermal components have heat generation and rejection models, as shown in Figure 10.

The heat equation for the engine can be expressed as:

\[ m_{\text{eng}} C_{\text{eng}} \dot{T}_{\text{eng}} = Q_{\text{fuel}} - P_{\text{work}} - Q_{\text{exhaust}} - Q_{\text{coolant}} - Q_{\text{air}} - Q_{\text{heating}} \]  

(1)

where \( T_{\text{eng}} \), \( C_{\text{eng}} \), and \( m_{\text{eng}} \) are the temperature, the specific heat capacity, and the mass of the engine, respectively. \( Q_{\text{fuel}} \) and \( P_{\text{work}} \) are the heat generated from the combustion process and the work converted to the mechanical system. \( Q_{\text{exhaust}} \), \( Q_{\text{coolant}} \), and \( Q_{\text{heating}} \) are the heat rejected by the emission gas, the coolant system, and the heat core, respectively. \( Q_{\text{air}} \) is the heat transferred to the air by the convection effect.

3.1.2 Transmission Thermal Model

An example of the thermal component model for transmission is shown in Figure 11, which is for a Toyota Prius HEV.
In the figure, the heat generated by motors, $Q_{mot1}$ and $Q_{mot2}$, and the loss by the gearbox, $Q_{gb\text{,}loss}$, are considered for heat sources. The heat rejected by the transmission oil loop and the convection heat transfer between the transmission and the air, $Q_{oil}$ and $Q_{air}$, are also considered as:

$$m_{tra}C_{tra}T_{tra} = Q_{mot1} + Q_{mot2} + Q_{gb\text{,}loss} - Q_{oil} - Q_{air} \tag{2}$$

where $T_{tra}$, $C_{tra}$, and $m_{tra}$ are the temperature, the specific heat capacity, and the mass of the transmission, respectively.

### 3.1.3 Cabin and Climate Control System

The climate control system (including the air conditioning system) and the heat balance of the cabin can be expressed as shown in Figure 12.

The cabin temperature can be calculated as:

$$m_{cab}C_{cab}T_{cab} = Q_{load} + Q_{hvac} - Q_{air} \tag{3}$$

where $T_{cab}$, $C_{cab}$, and $m_{cab}$ are the temperature, the specific heat capacity, and the mass of the cabin air, respectively. $Q_{hvac}$ is the heat controlled by the climate control system, and $Q_{air}$ is the heat convectively transferred between the cabin system and the ambient air. Further, the heat load, $Q_{load}$, includes the solar heat load, passenger heat load, and heat transferred from powertrain components.

### 3.1.4 Battery Thermal Model

The battery model has the heat source and heat rejection model as well (Figure 13). The heat is generated by the electrochemical and electrical loss, which is calculated by the voltage drop and the output current.

The equation for the battery temperature can be expressed as:

$$m_{ess}C_{ess}T_{ess} = Q_{pol} + Q_{res} - Q_{cooling} \tag{8}$$

where $T_{ess}$, $C_{ess}$, and $m_{ess}$ are the temperature, the specific heat capacity, and the mass of the battery, respectively. The two heat sources terms, $Q_{pol}$ and $Q_{res}$, are calculated from PNGV model with parameters estimated from the test data [11].

### 3.2 Control Model

Figure 14 shows an example of a control model, which is for a Toyota Prius PHEV.

In the example, the controller determines the operating mode — like charge depleting (CD) or charge sustaining (CS) — according to the SOC, and it turns on the engine if the demand power exceeds the threshold power. Moreover, the thermal conditions, such as the engine coolant temperature or the battery temperature, also affect the control flow, as shown in Figure 14. Each vehicle model should have its own controller to properly operate the powertrain components, and the controller should reproduce the real world control behaviors well.

### 4 Vehicle System and Validation

The vehicle model can be completed by integrating all the powertrain components and the controller into the system model. Figure 15 shows an example for a Toyota Prius HEV.
Autonomie, which was developed by Argonne for vehicle simulations, is used to integrate all the component models, and the vehicle models are validated with the test data by comparing the fuel consumption obtained from the simulation model with the fuel consumption measured in the tests, which are shown in Figure 16.

The comparison results show that the simulation models are able to represent the impact of the thermal conditions on the fuel consumption across the vehicle configurations quite well. Based on the comparison, it can be said that the simulation techniques are appropriate for evaluating the vehicle’s fuel consumption according to different thermal conditions.

5 Conclusion

The main goal of this brief is to describe the entire process for developing thermal management systems for advanced vehicles. First, vehicles should be tested under well-organized test procedures, so that the impact of the different thermal conditions on the vehicle’s performance can be seen. Second, the test data should be appropriately analyzed to elicit an understanding of the performance of the powertrain components and the vehicle’s control behaviors. Third, simulation models should be developed based on the analyzed results and be well validated with the test results. Argonne National Laboratory, by following these processes, developed several configurations for advanced vehicles, and the validation results show that the simulation models appropriately calculate the fuel consumption of the vehicles under different thermal conditions. The developed vehicles can be used in many other studies, so that the impact of thermal conditions can be analyzed in various types of studies.

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References


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